

FIG. 1



FIG. 2B



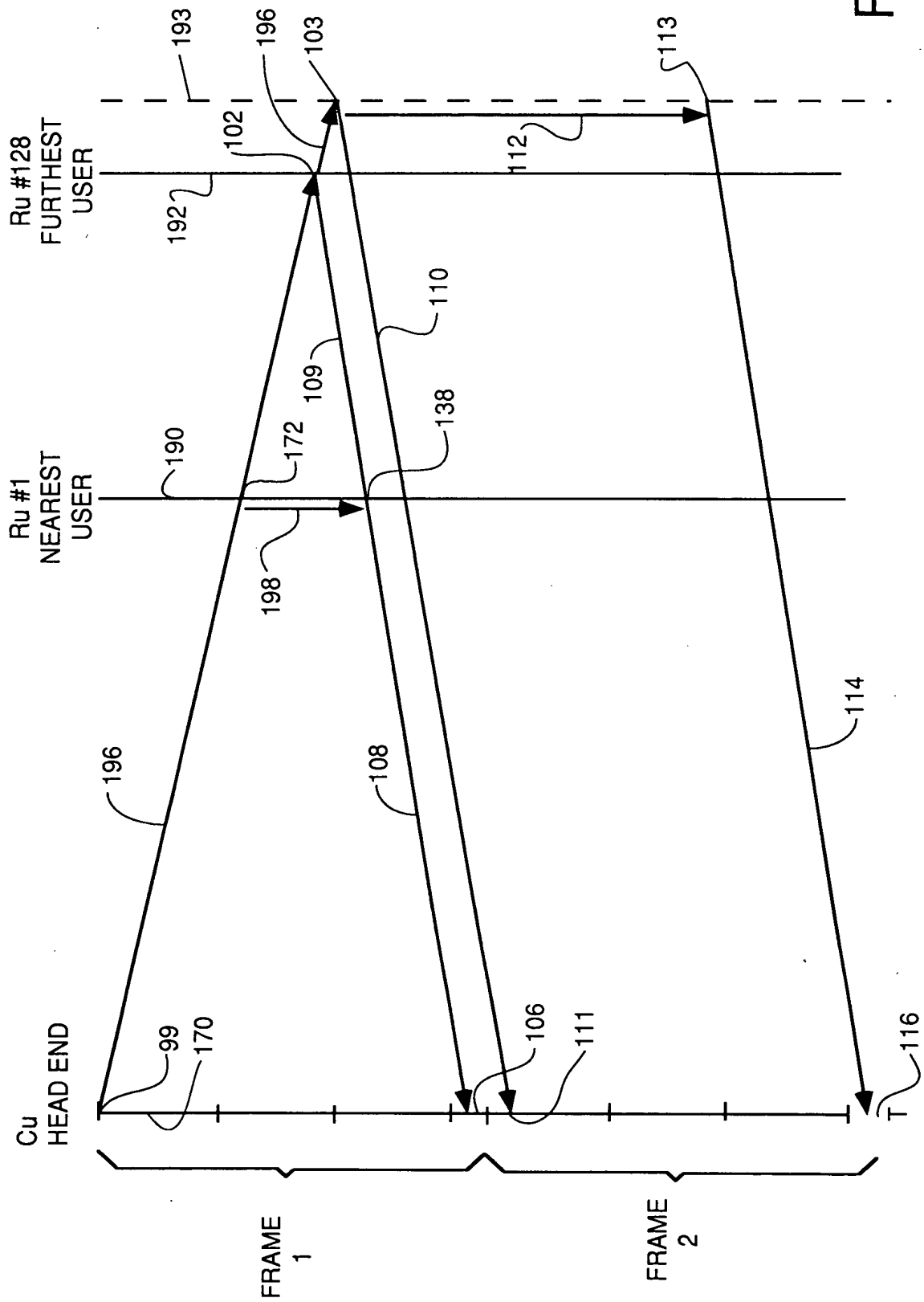


FIG. 3

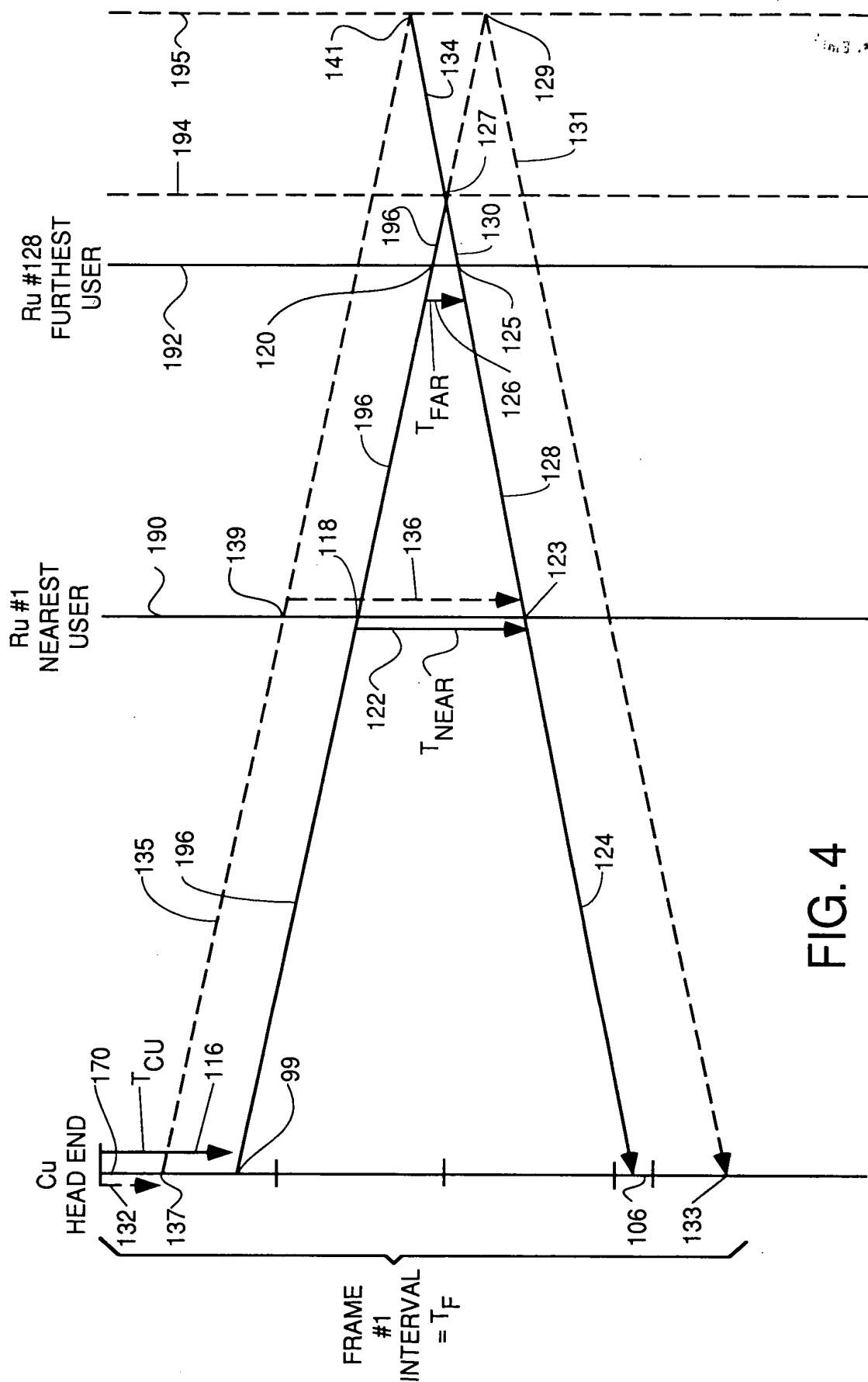
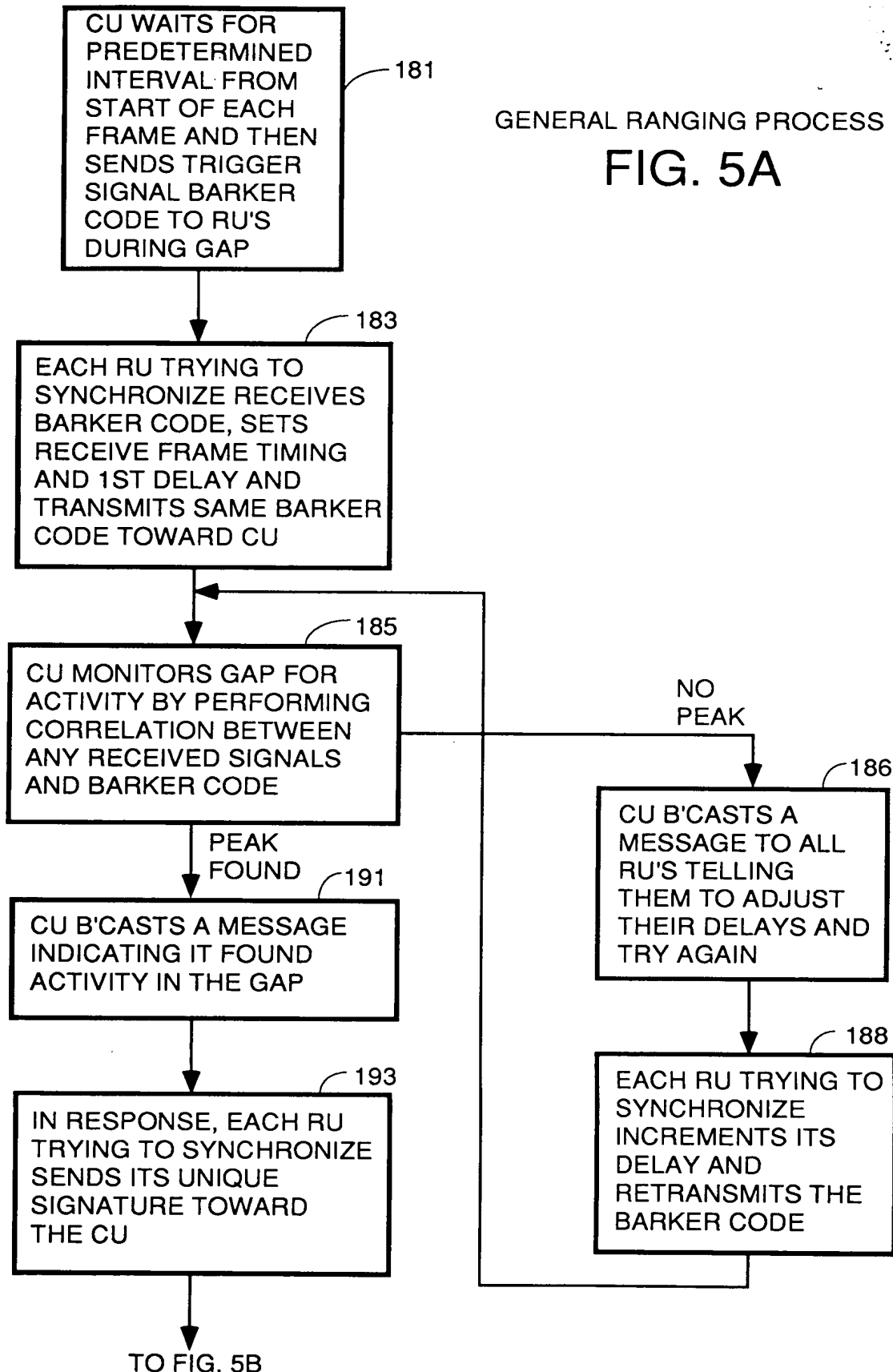


FIG. 4

GENERAL RANGING PROCESS

FIG. 5A



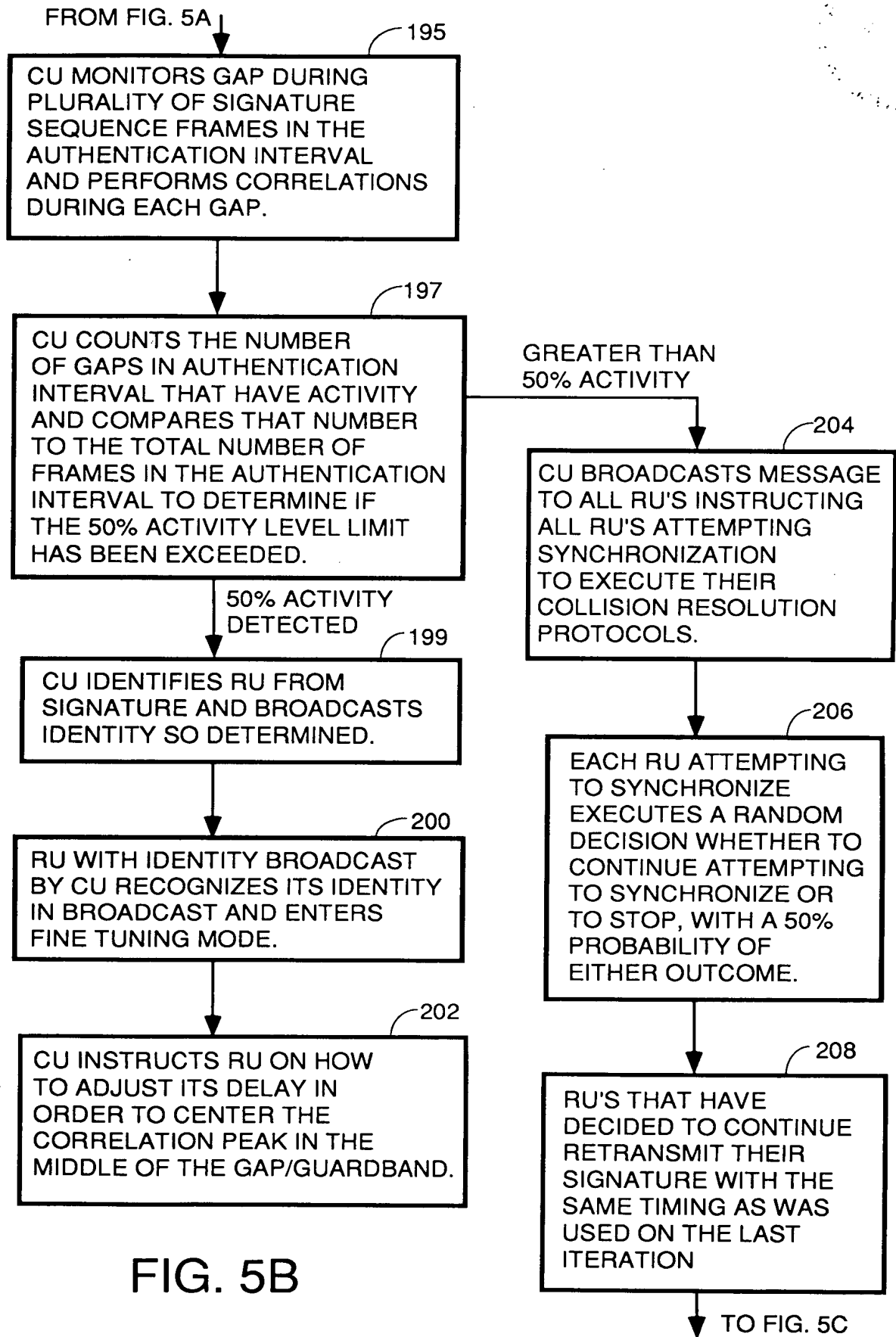


FIG. 5B

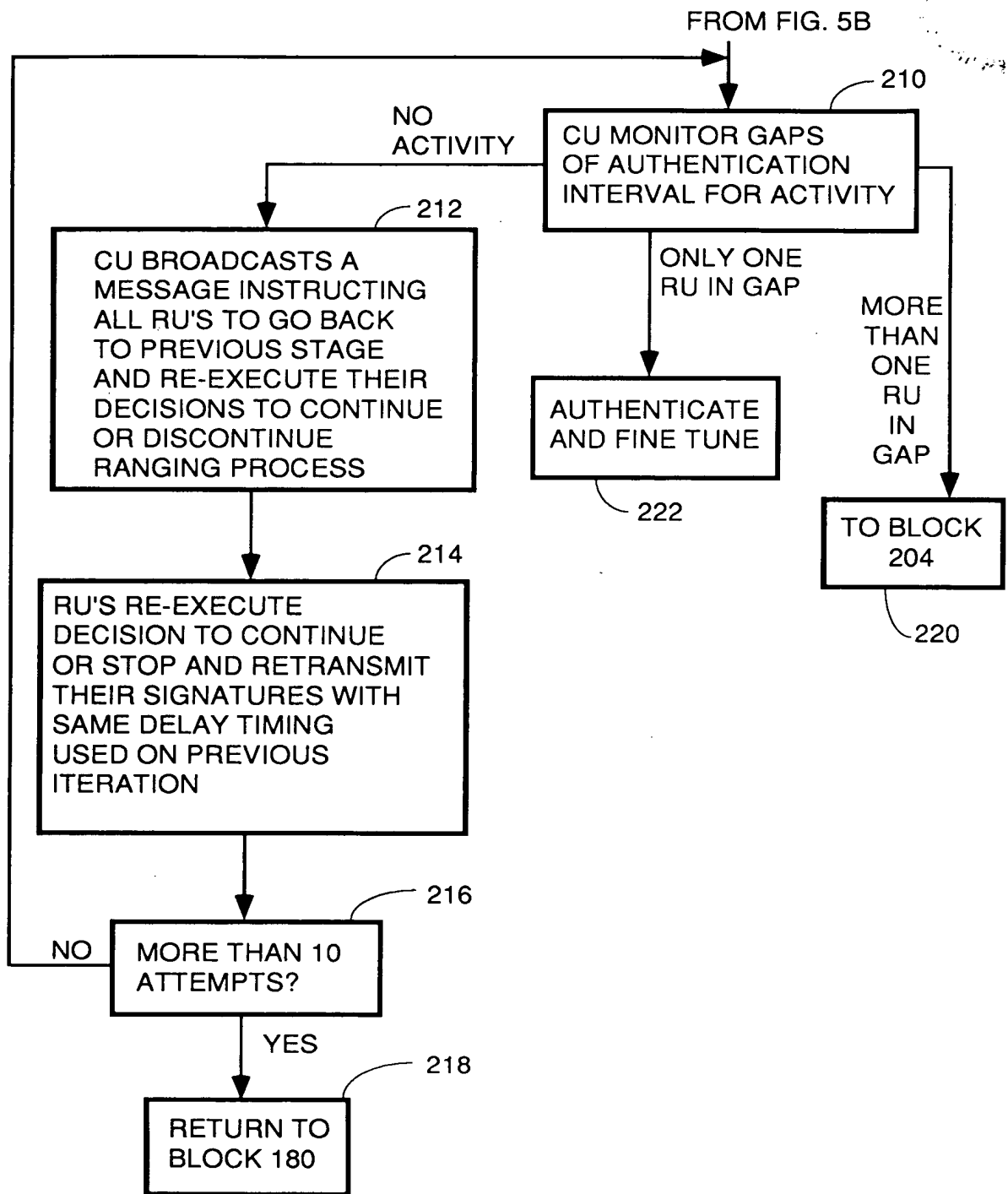


FIG. 5C

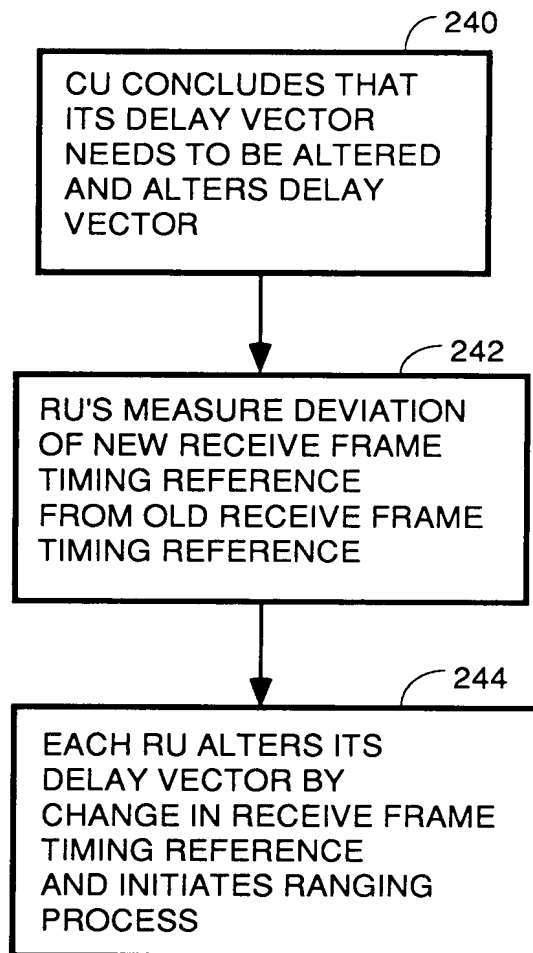


FIG. 6
DEAD RECKONING RE-SYNC

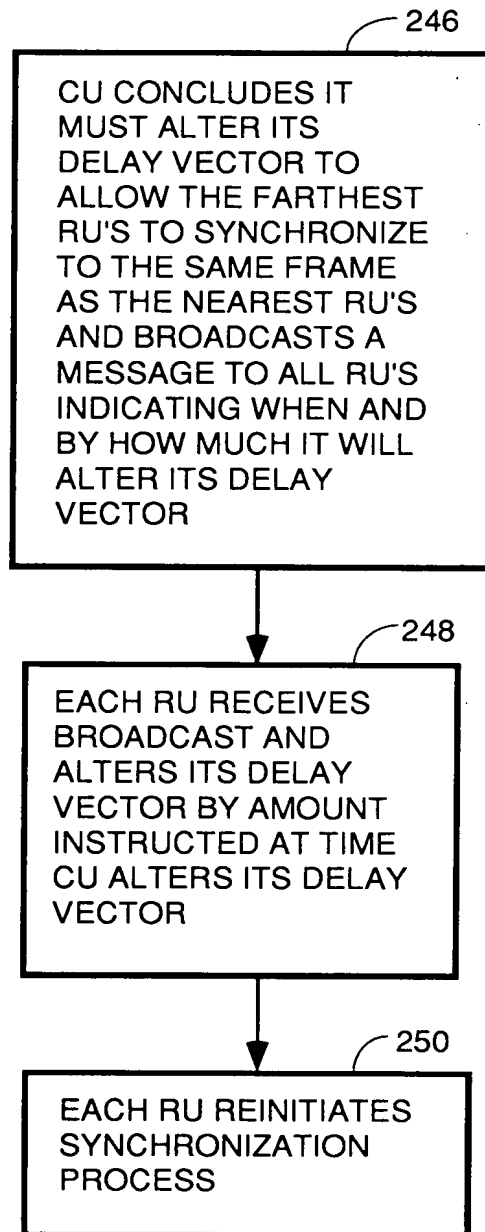
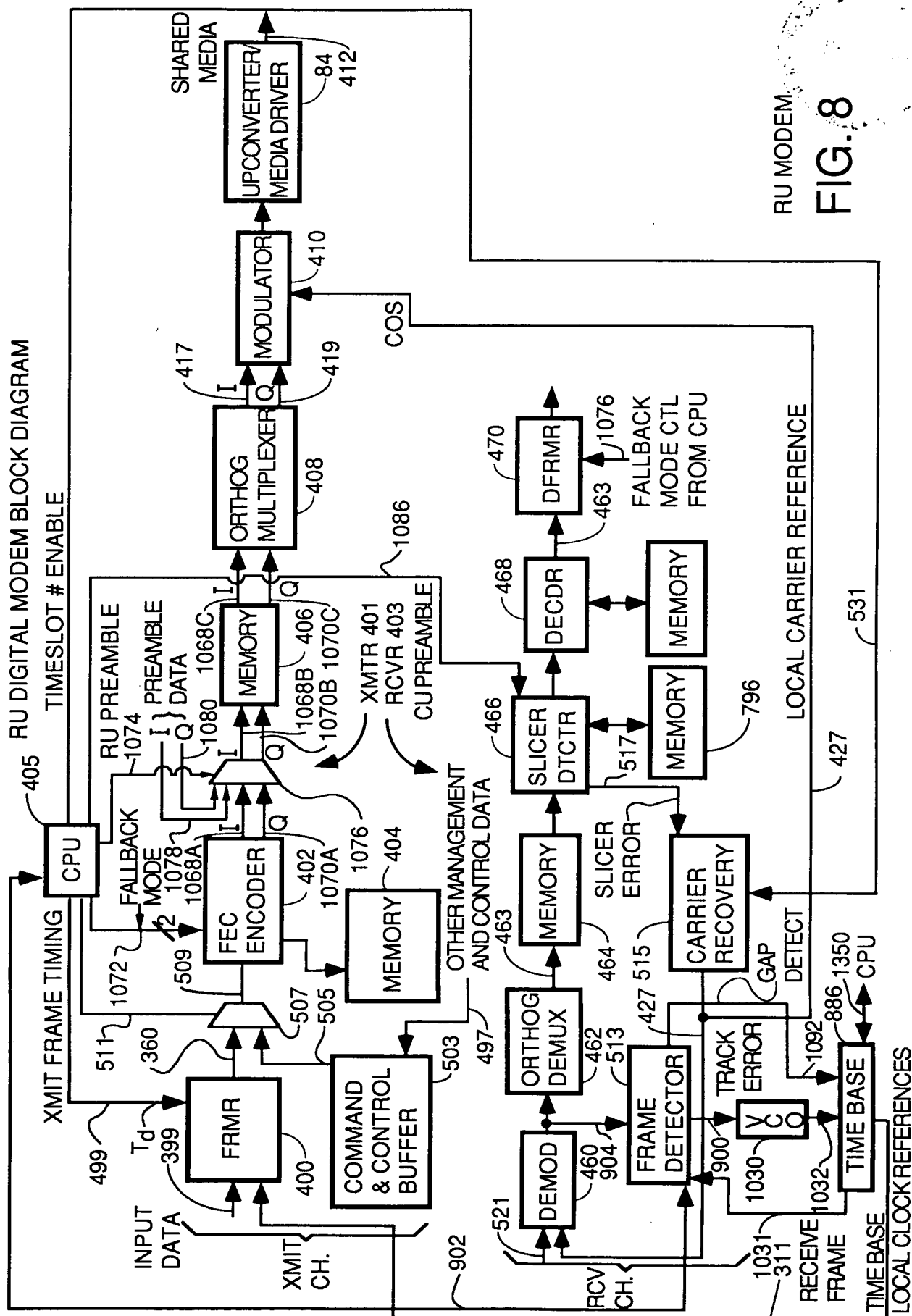


FIG. 7
PRECURSOR EMBODIMENT



RU MODEM.

FIG. 8

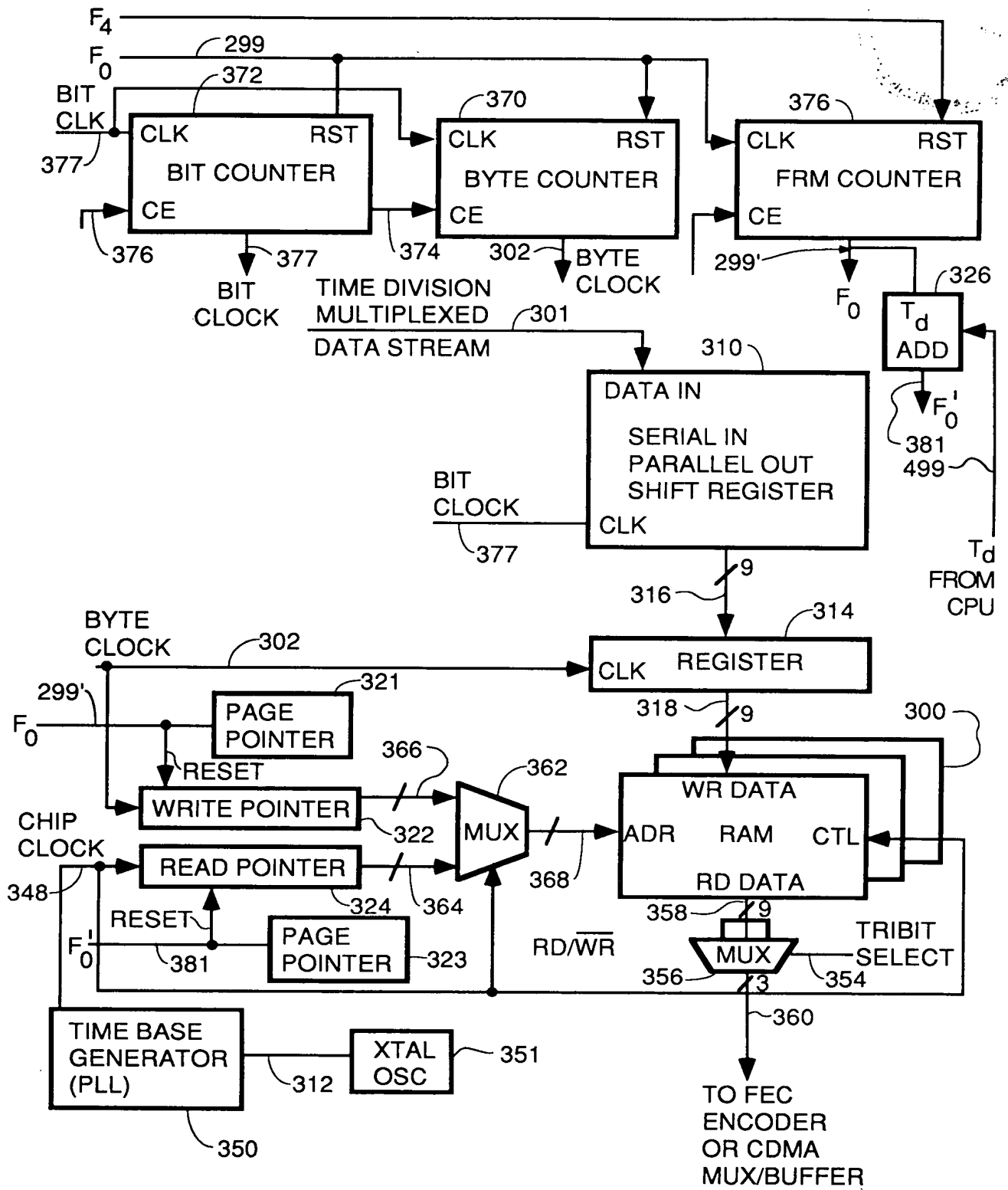


FIG. 9

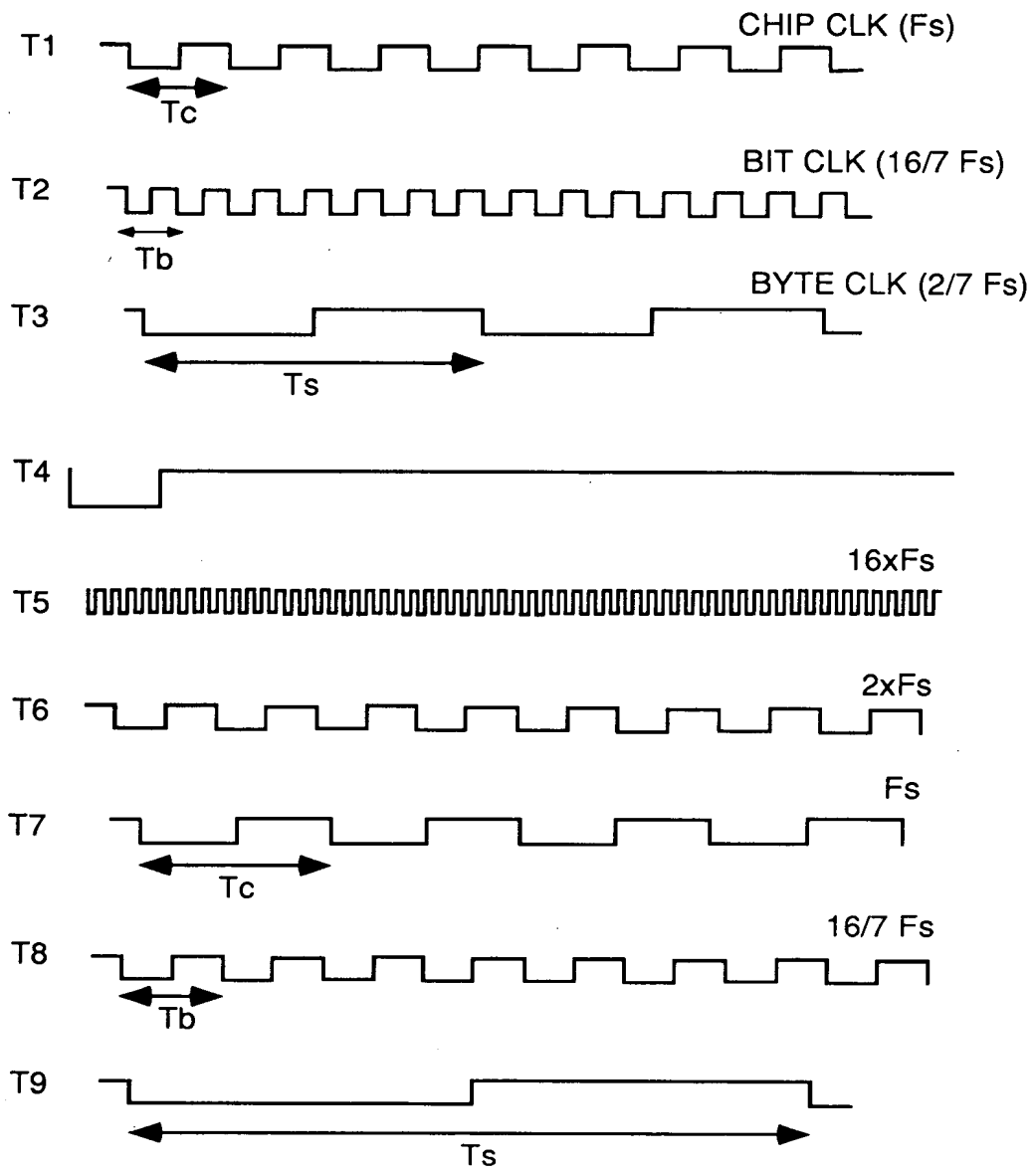


FIG. 10

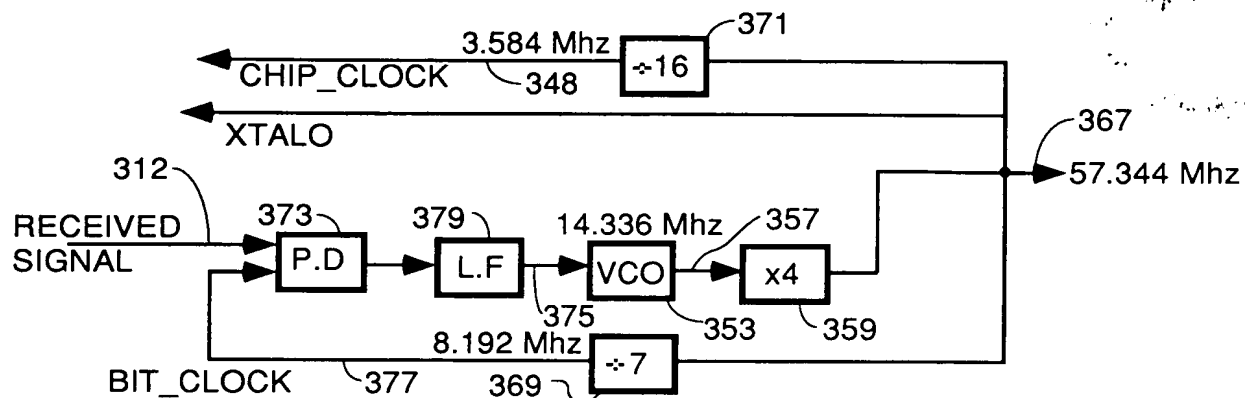


FIG. 11

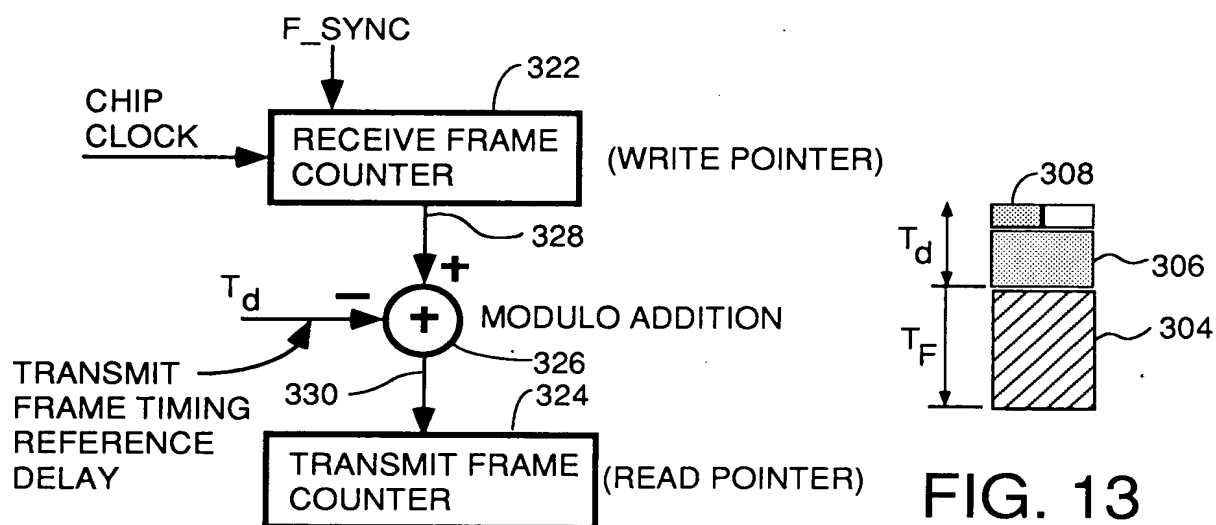


FIG. 13

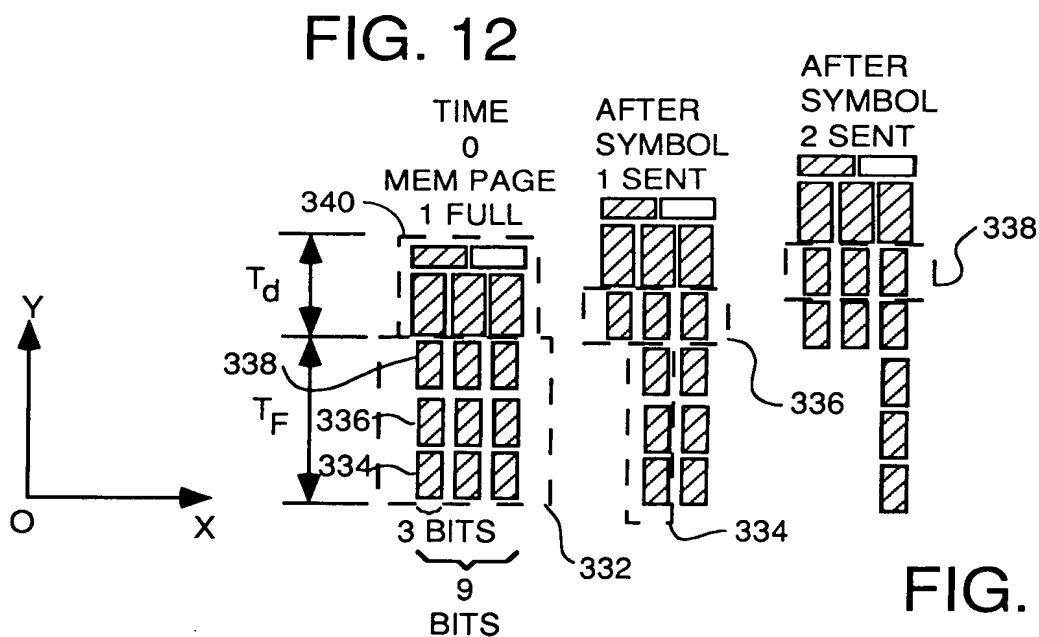


FIG. 14

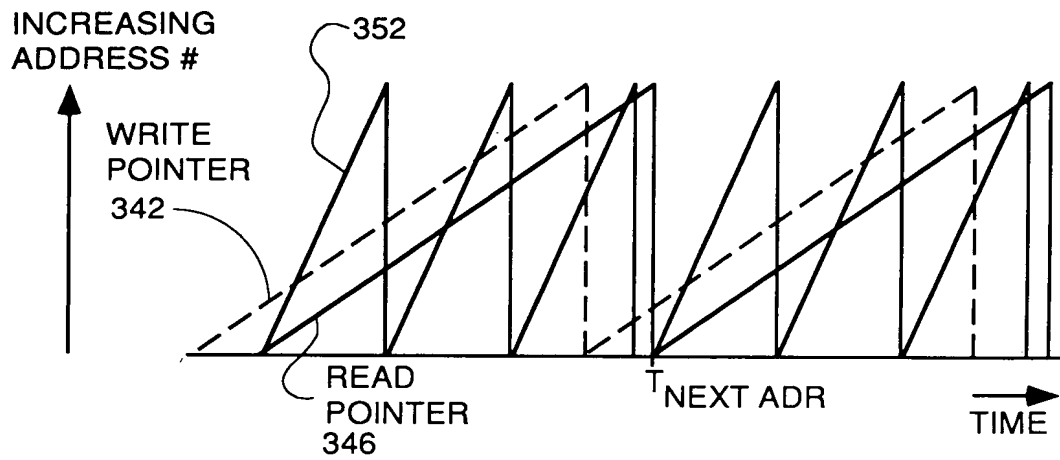


FIG. 15

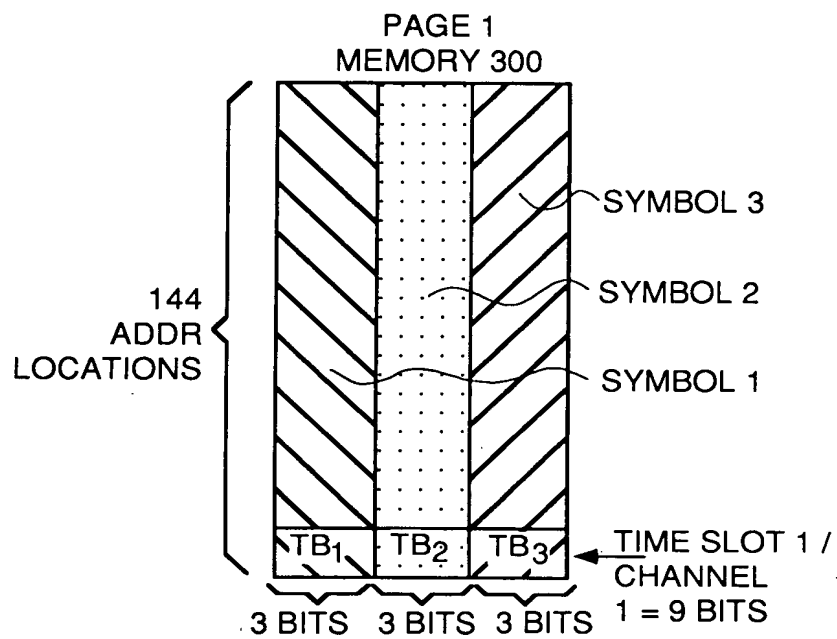
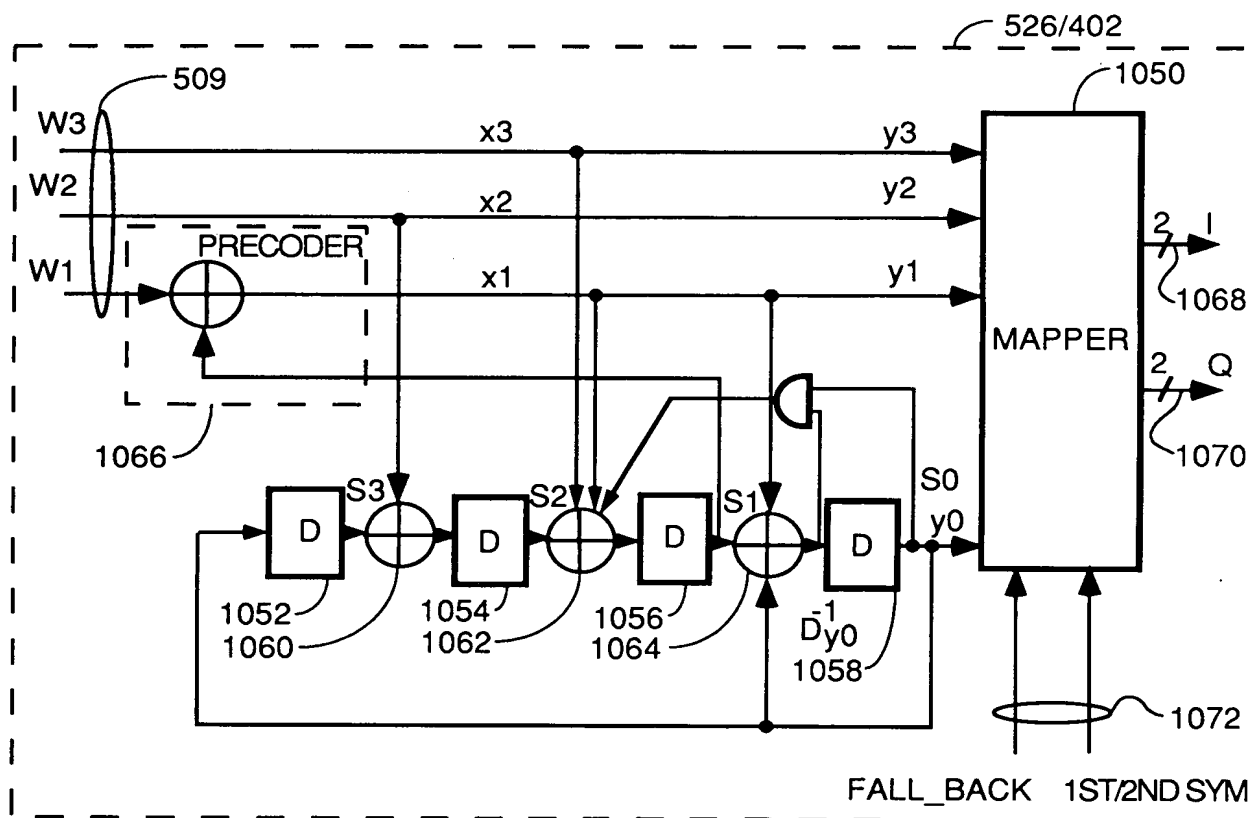


FIG. 16



PREFERRED TRELLIS ENCODER
FIG. 17

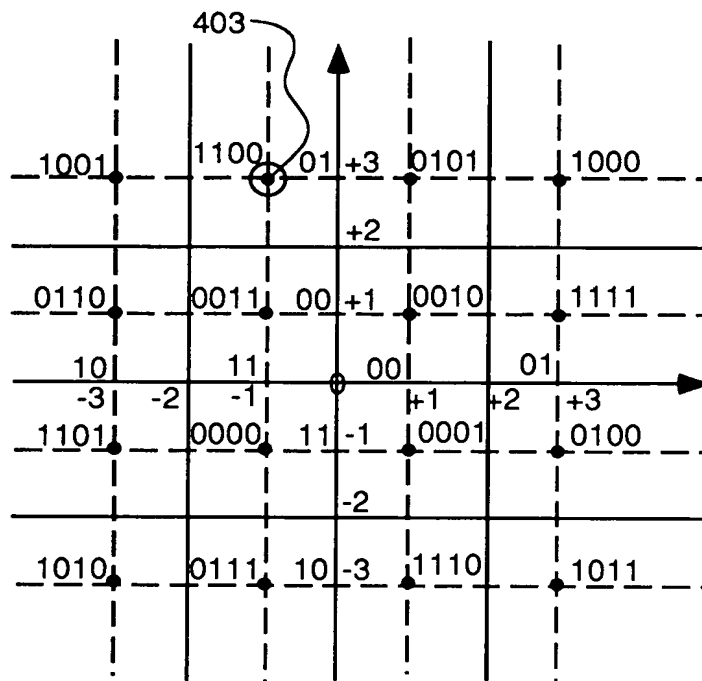


FIG. 18

0000	111	111	
0001	001	111	$= 1 - j$
0010	001	001	$= 1 + j$
0011	111	001	$= -1 + j$
0100	011	111	$= 3 - j$
0101	001	011	$= 1 + 3*j$
0110	101	001	$= -3 + j$
0111	111	101	$= -1 - 3*j$
1000	011	011	$= +3 + 3*j$
1001	101	011	$= -3 + 3*j$
1010	101	101	$= -3 - 3*j$
1011	011	101	$= 3 - 3*j$
1100	111	011	$= -1 + 3*j$
1101	101	111	$= -3 - j$
1110	001	101	$= 1 - 3*j$
1111	011	001	$= 3 + j$

FIG. 19

INFORMATION
VECTOR [B]
FOR EACH
SYMBOL

ORTHOGONAL
CODE MATRIX

$$\begin{array}{c} 483 \\ 481 \end{array} \begin{bmatrix} 0 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ \vdots & & & \end{bmatrix} \times \begin{bmatrix} C_{1,1} & C_{1,2} & \cdots & C_{1,144} \\ C_{2,1} & C_{2,2} & \cdots & C_{2,144} \\ \vdots & \vdots & & \vdots \end{bmatrix}$$

FIG. 20A

REAL
PART OF
INFO
VECTOR
[b] FOR
FIRST
SYMBOL

REAL
PART OF
RESULT
VECTOR

$$\begin{array}{c} 405 \end{array} \begin{bmatrix} +3 \\ -1 \\ -1 \\ +3 \end{bmatrix} \cdot \begin{array}{c} 407 \\ \begin{bmatrix} 1 & 1 & 1 & 1 \\ -1 & -1 & 1 & 1 \\ -1 & 1 & -1 & 1 \\ -1 & 1 & 1 & -1 \end{bmatrix} \end{array} = \begin{array}{c} 409 \\ \begin{bmatrix} 4 \\ 0 \\ 0 \\ -8 \end{bmatrix} \end{array}$$

$[b_{\text{REAL}}] \times [\text{CODE MATRIX}] = [R_{\text{REAL}}] = \text{"CHIPS OUT" ARRAY-REAL}$

FIG. 20B

MAPPING FOR FALL-BACK MODE - LSB'S

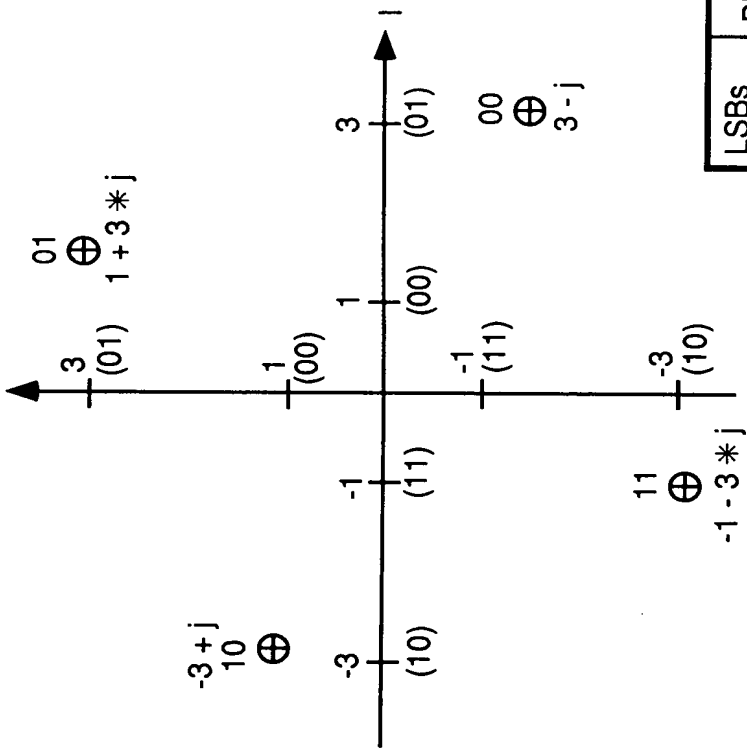


FIG. 21

LSBs y1 y0	PHASE	1+jQ
00	0	3-j
01	90	1+j3
10	180	-3+j
11	-90	-1-j3

MSBs y3 y2	PHASE difference (2nd-1st symbol)	1+jQ WHEN LSB=00	1+jQ WHEN LSB=01	1+jQ WHEN LSB=10	1+jQ WHEN LSB=11
00	0	3-j	1+j3	-3+j	-1-j3
01	90	1+j3	-3+j	-1-j3	3-j
10	180	-3+j	-1-j3	3-j	1+j3
11	-90	-1-j3	3-j	1+j3	-3+j

LSB & MSB FALLBACK MODE MAPPINGS

FIG. 22

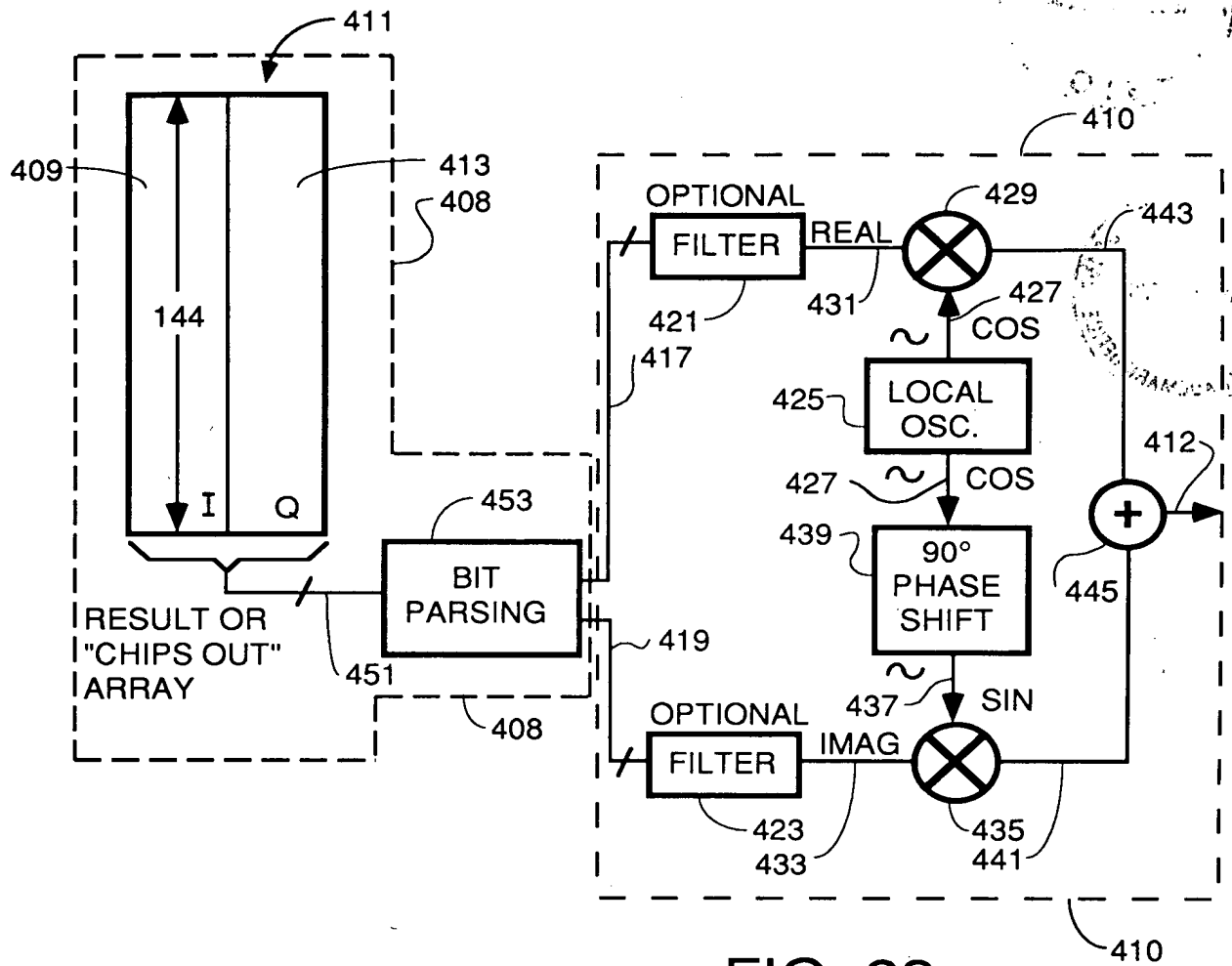


FIG. 23

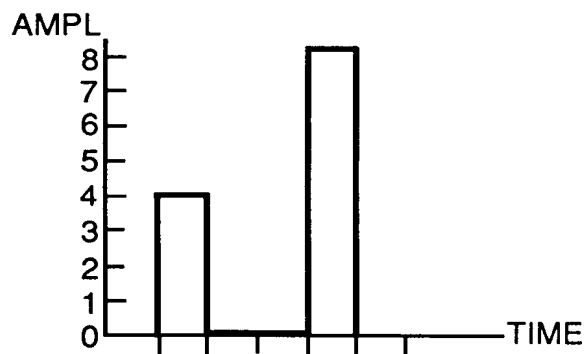


FIG. 24

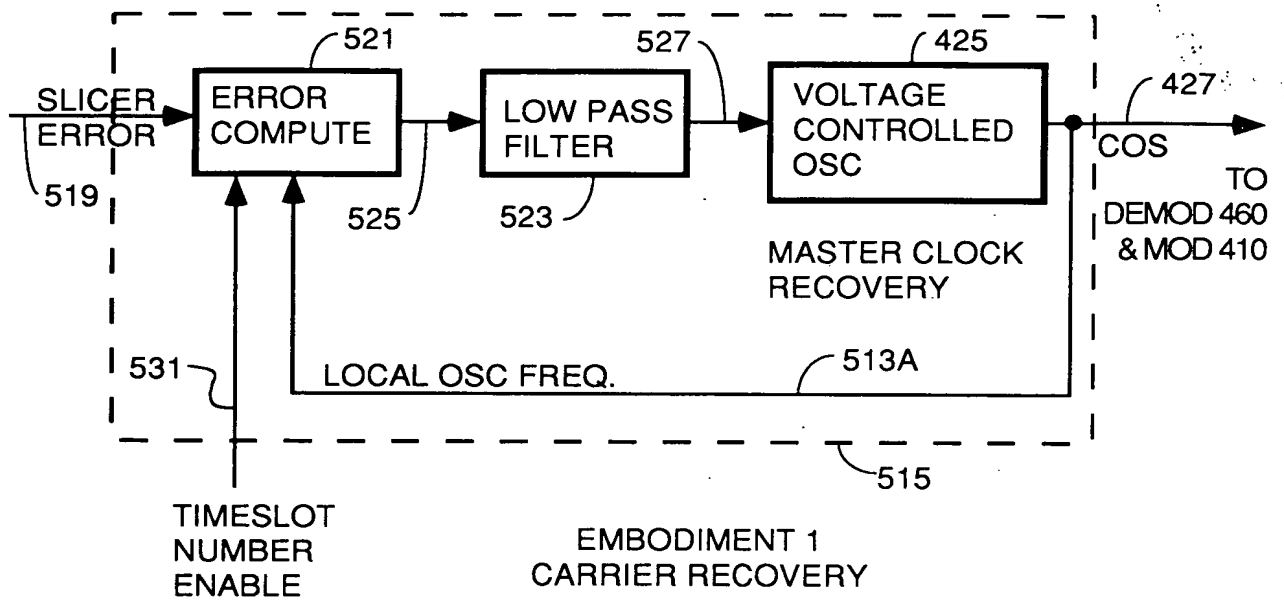


FIG. 25

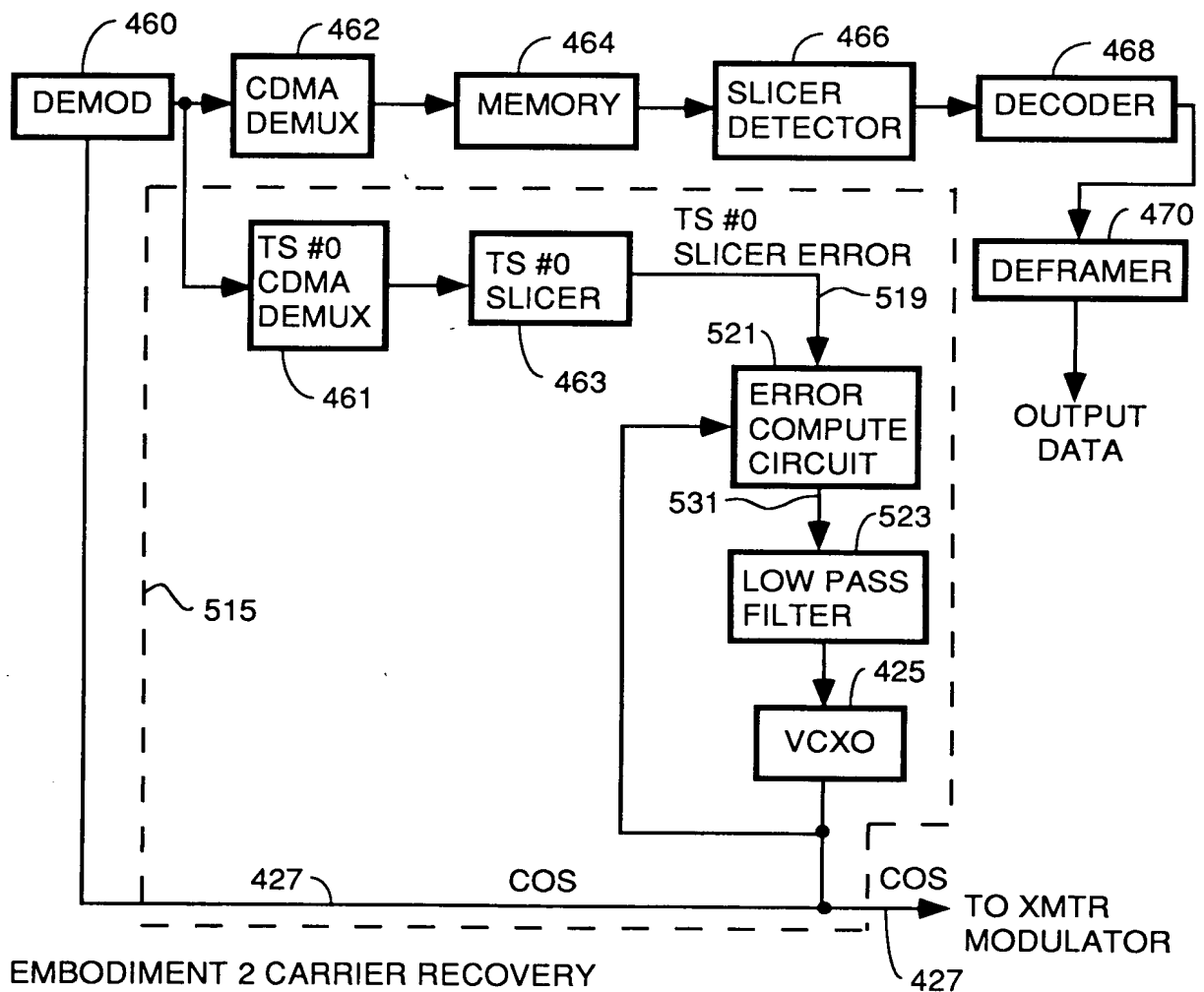


FIG. 26

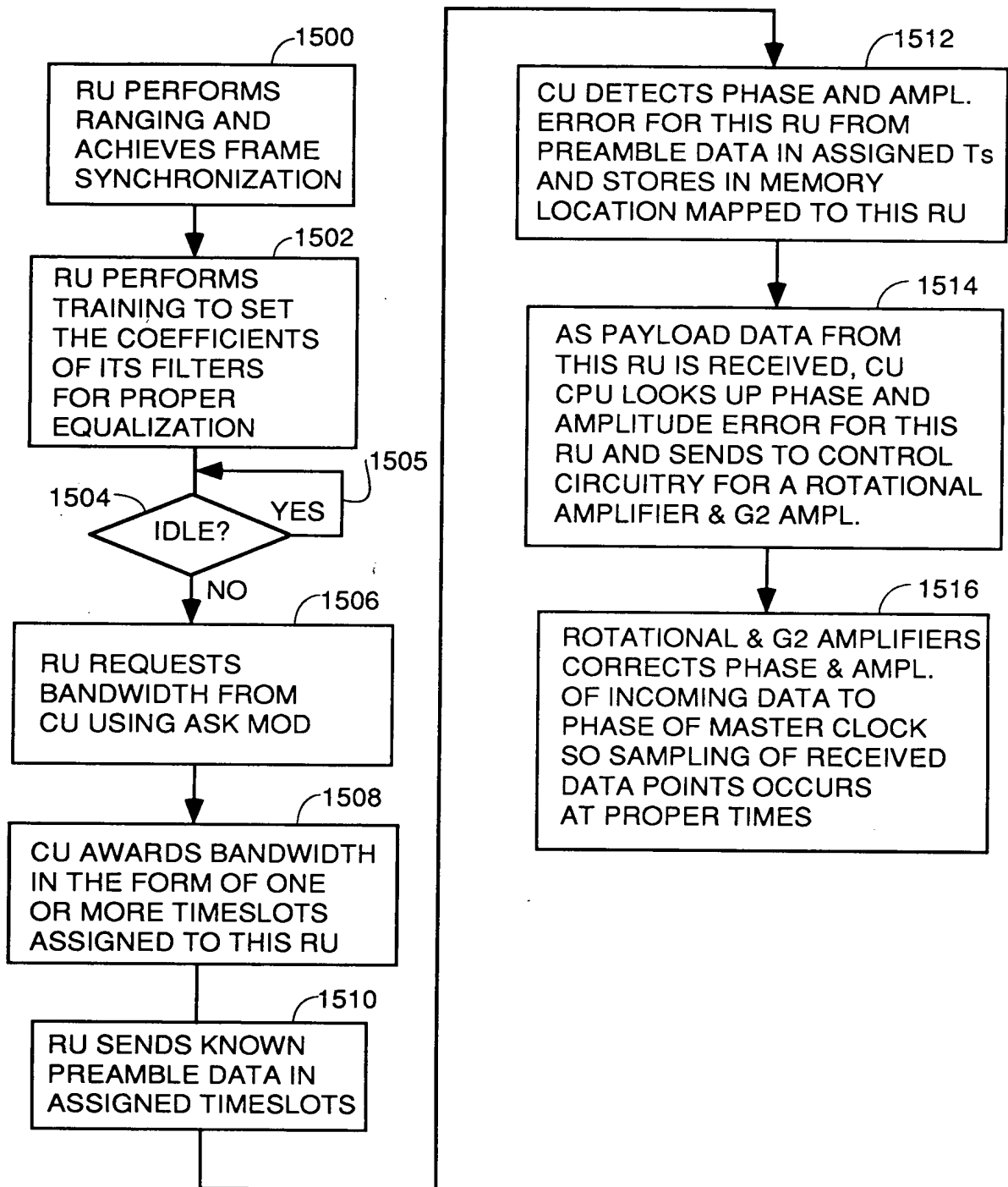
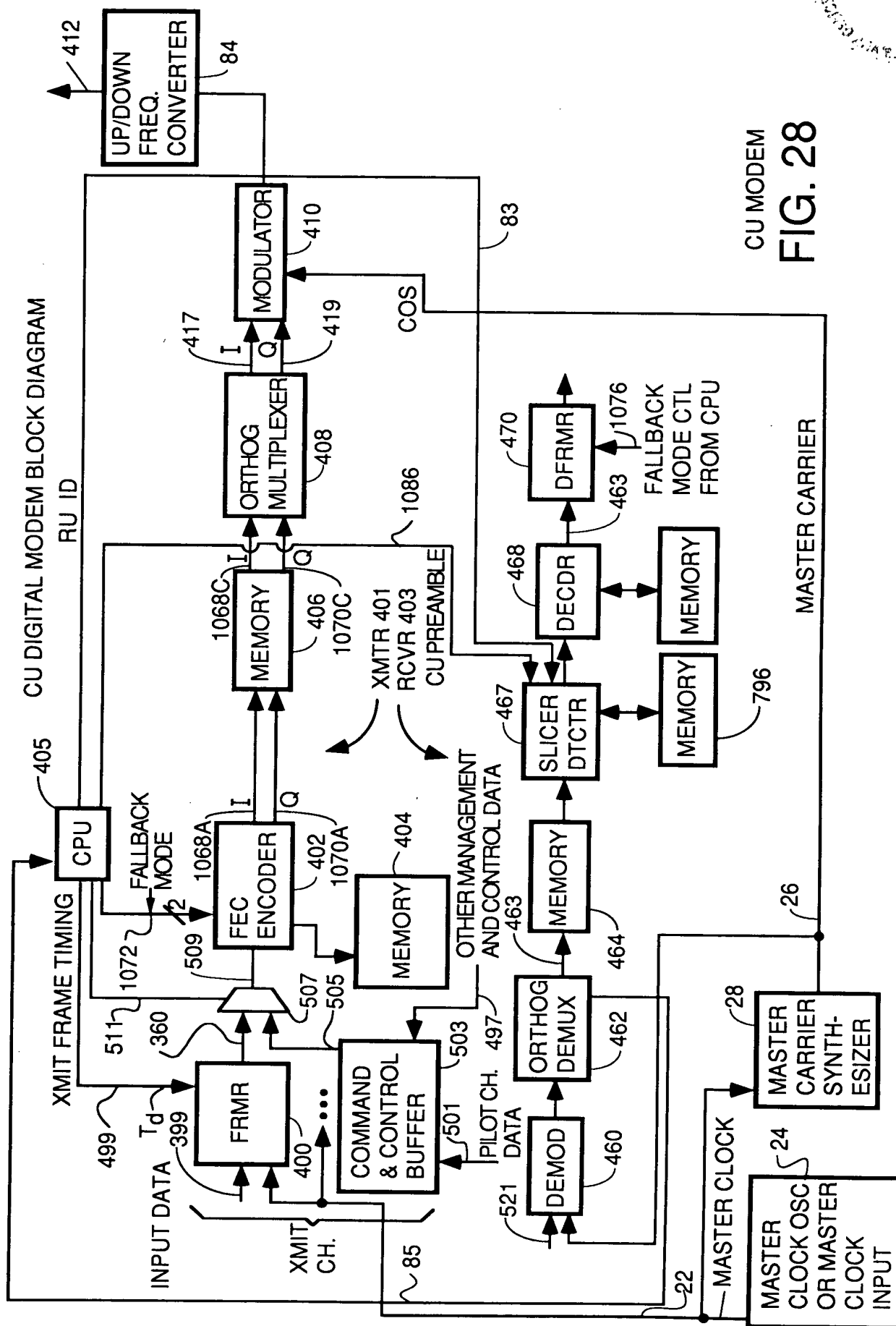


FIG. 27



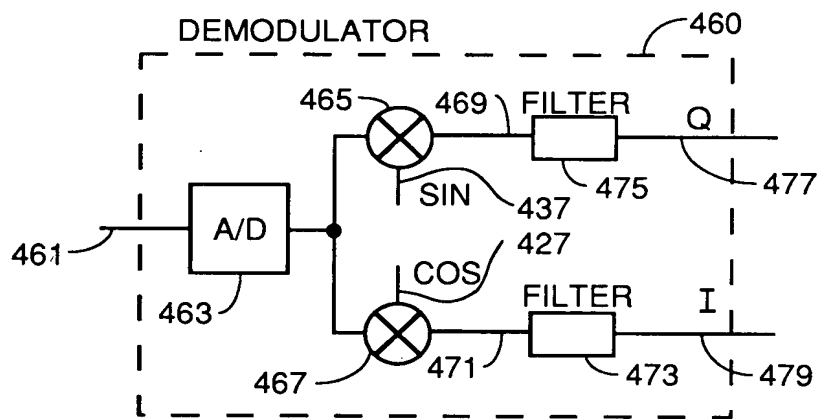
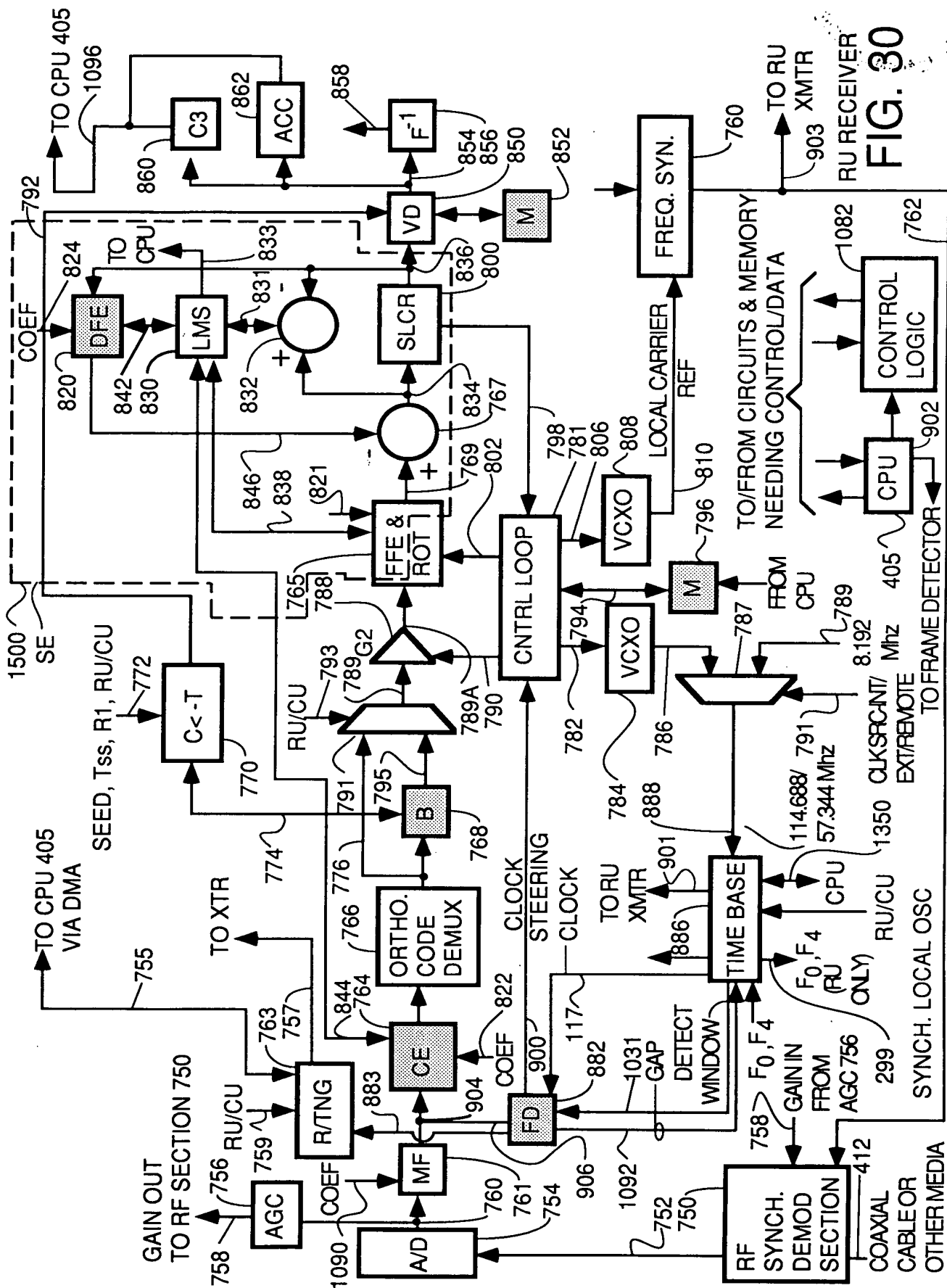
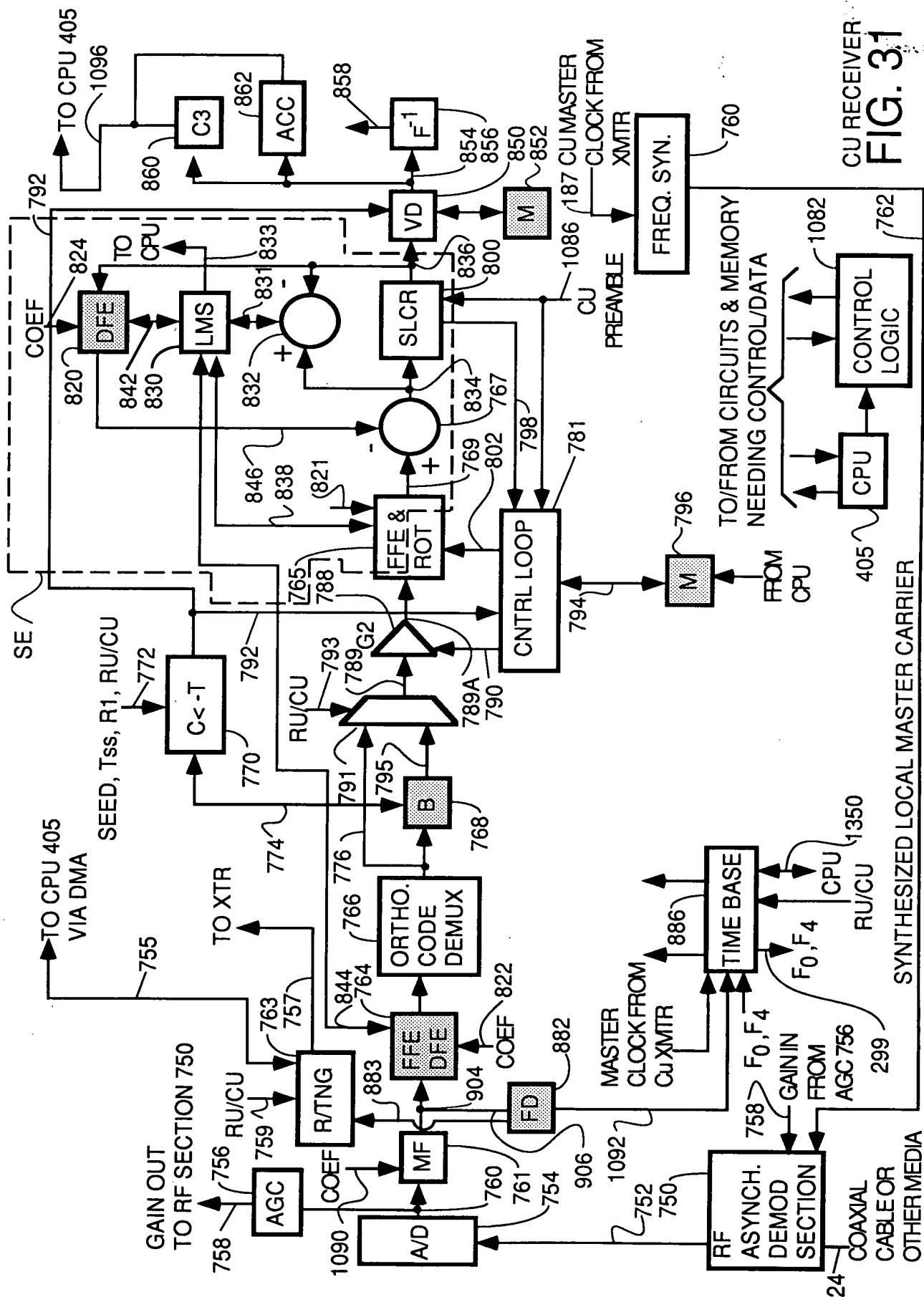
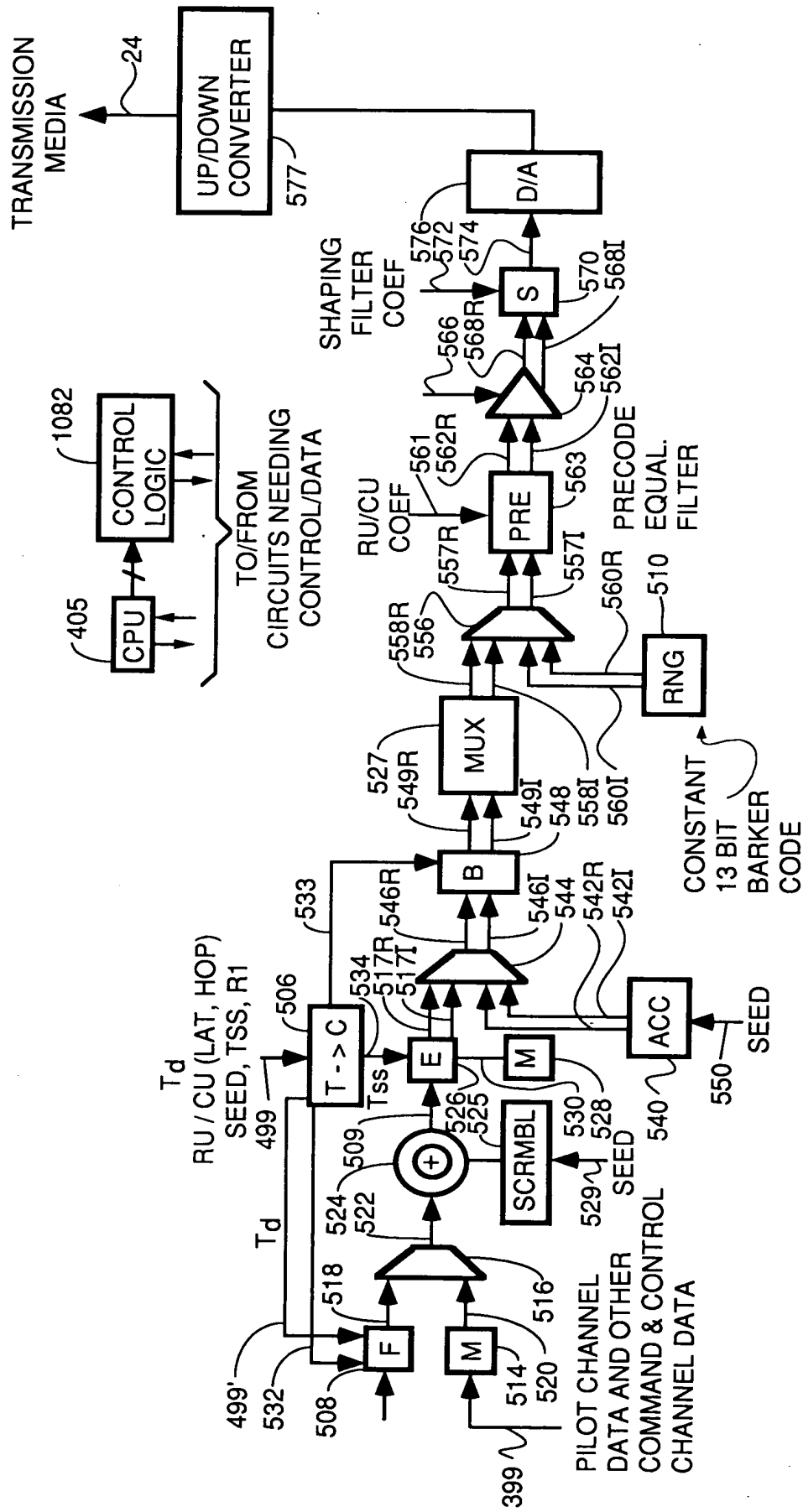


FIG. 29

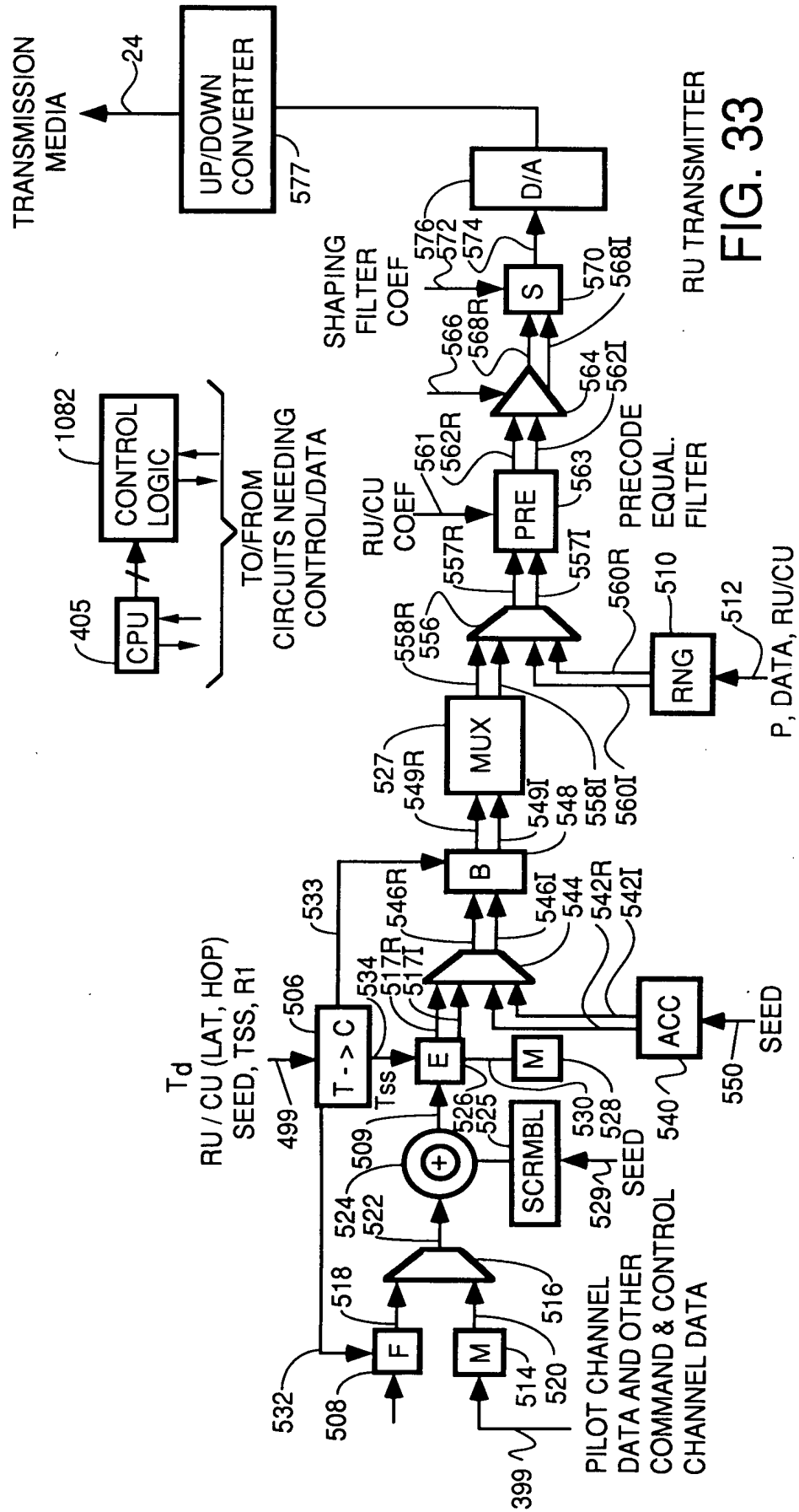


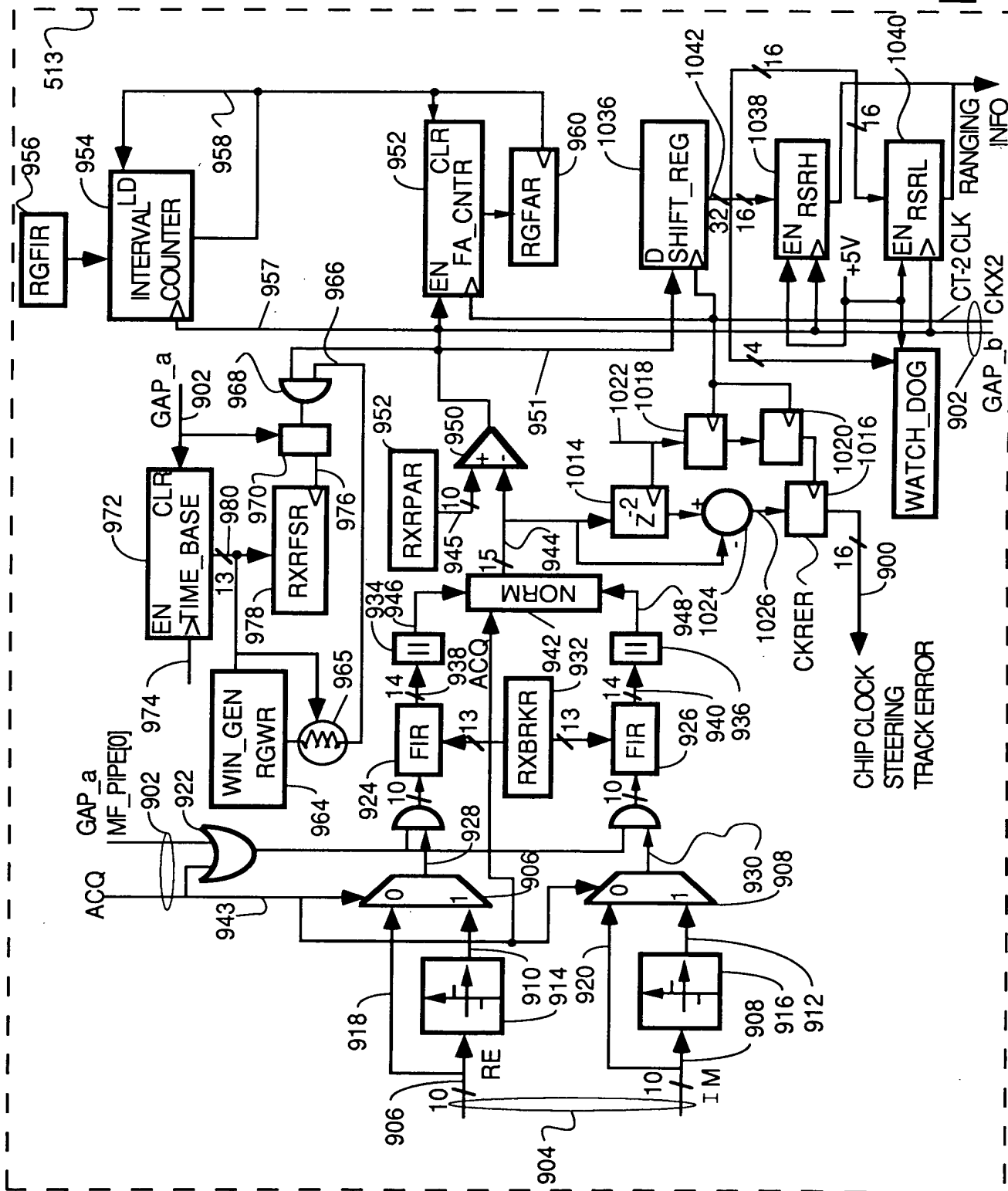




CU TRANSMITTER

FIG. 32





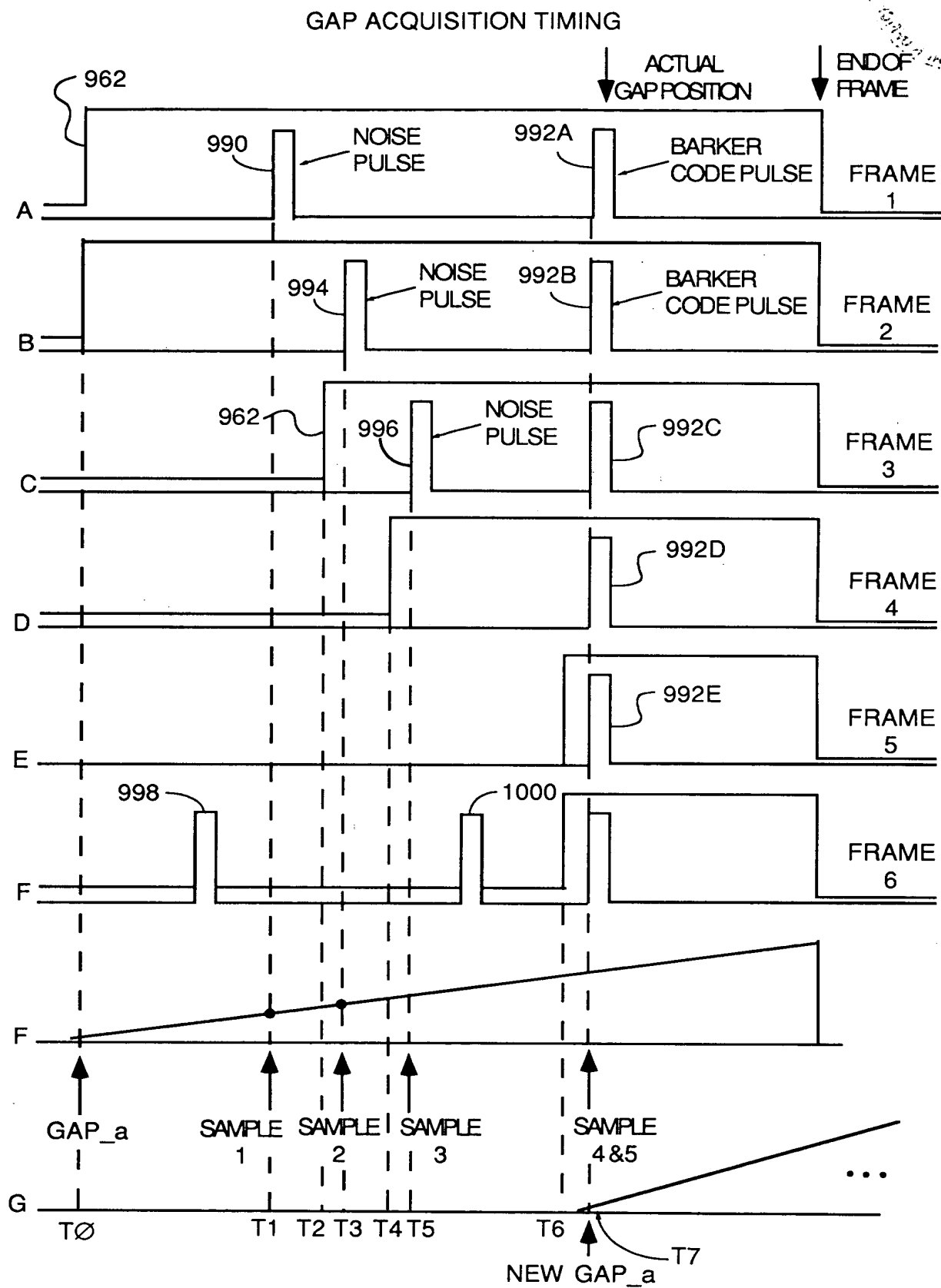


FIG. 35

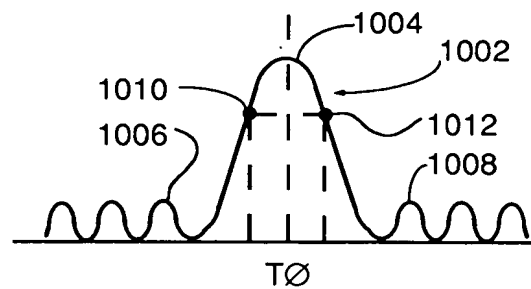


FIG. 36

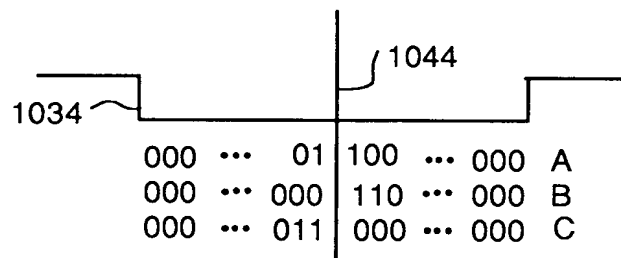


FIG. 37
FINE TUNING TO
CENTER BARKER CODE

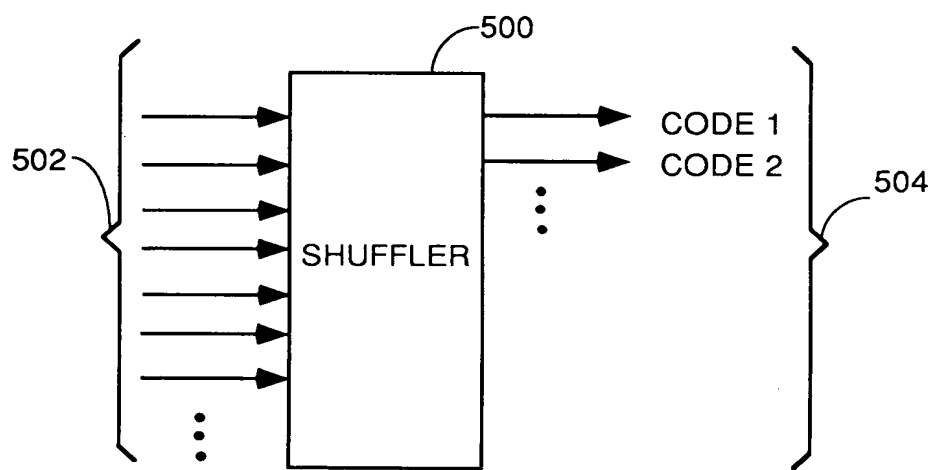


FIG. 38

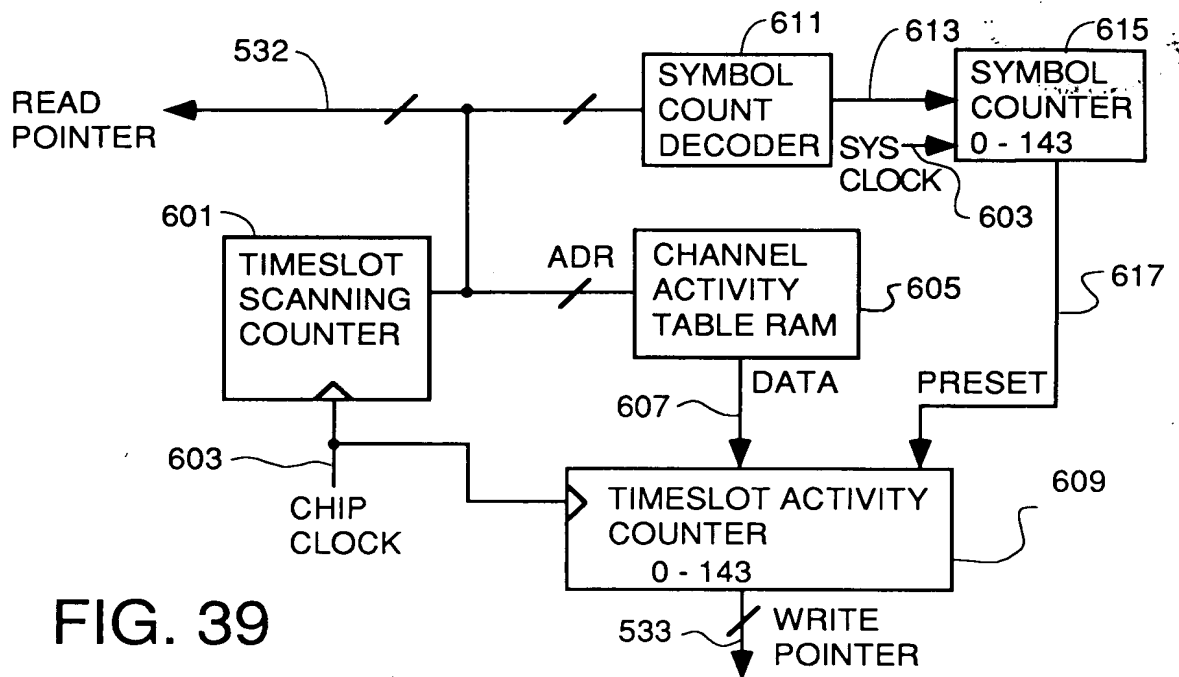


FIG. 39

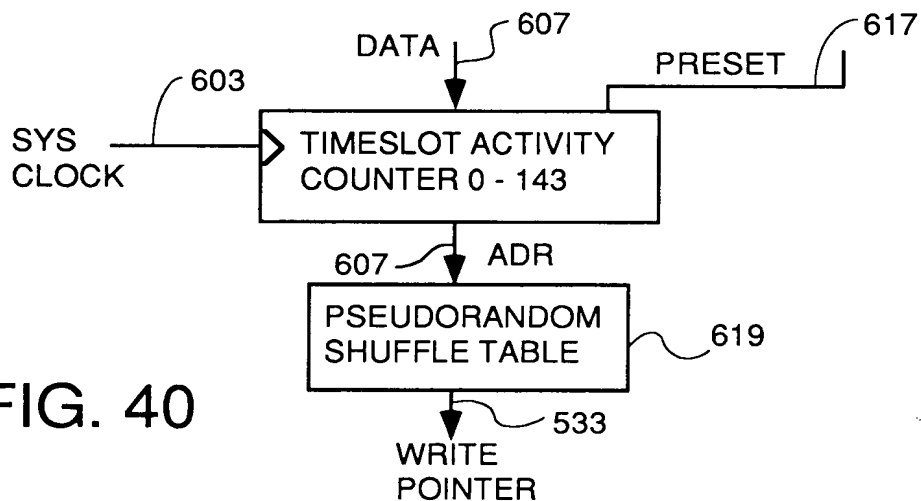


FIG. 40

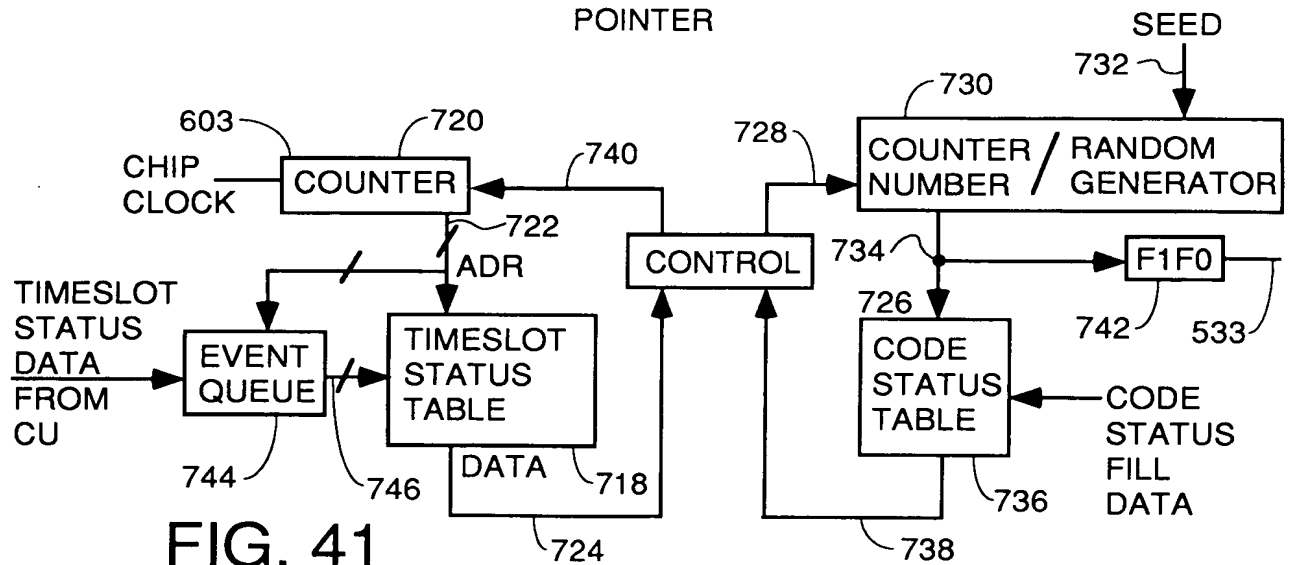


FIG. 41

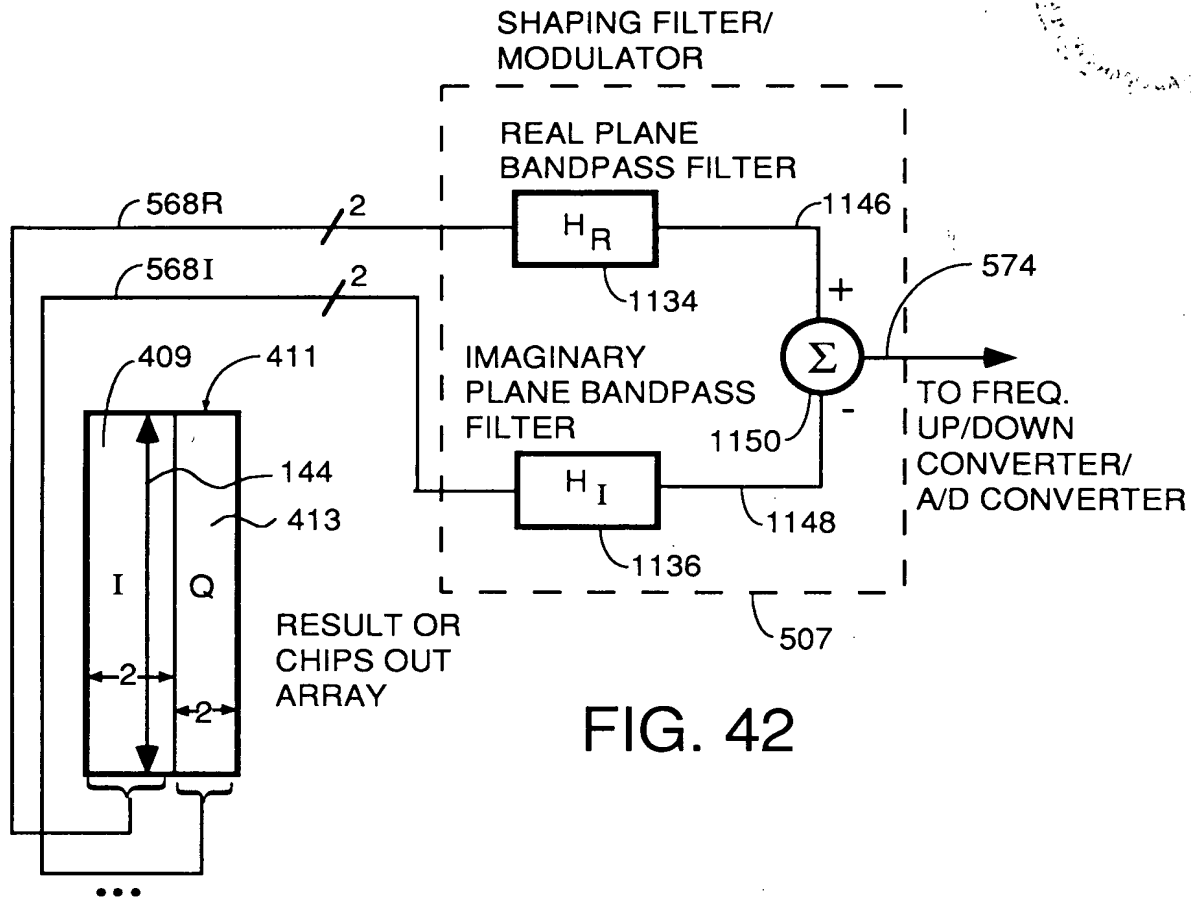


FIG. 42

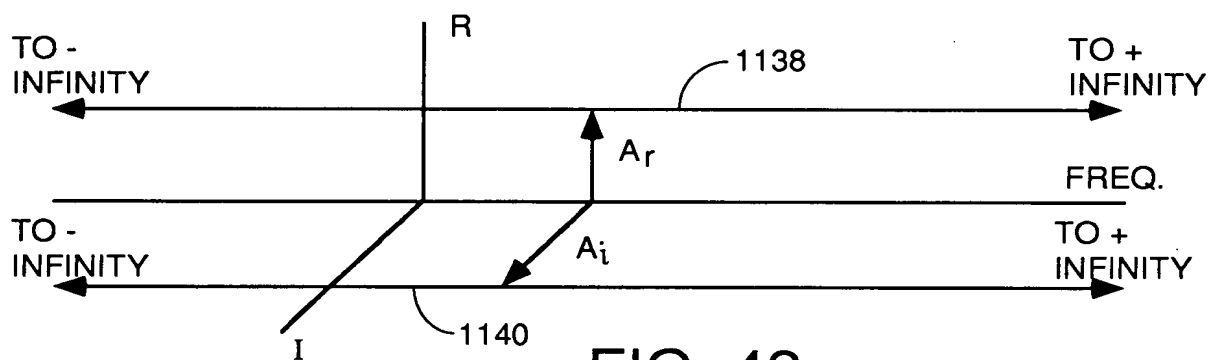


FIG. 43

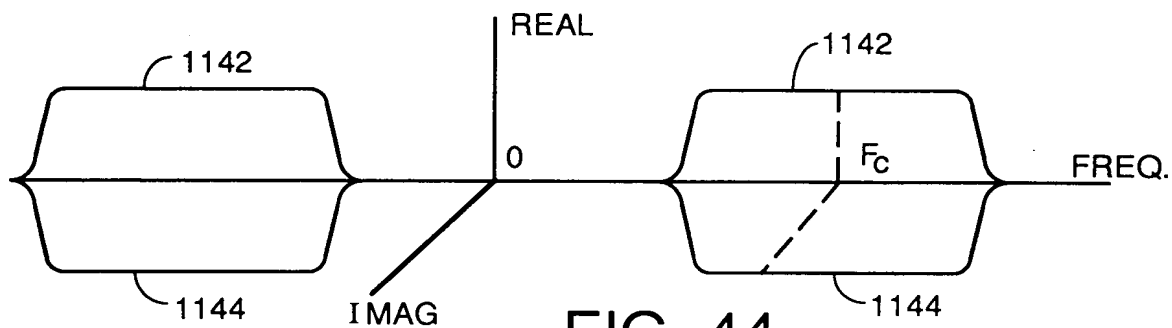
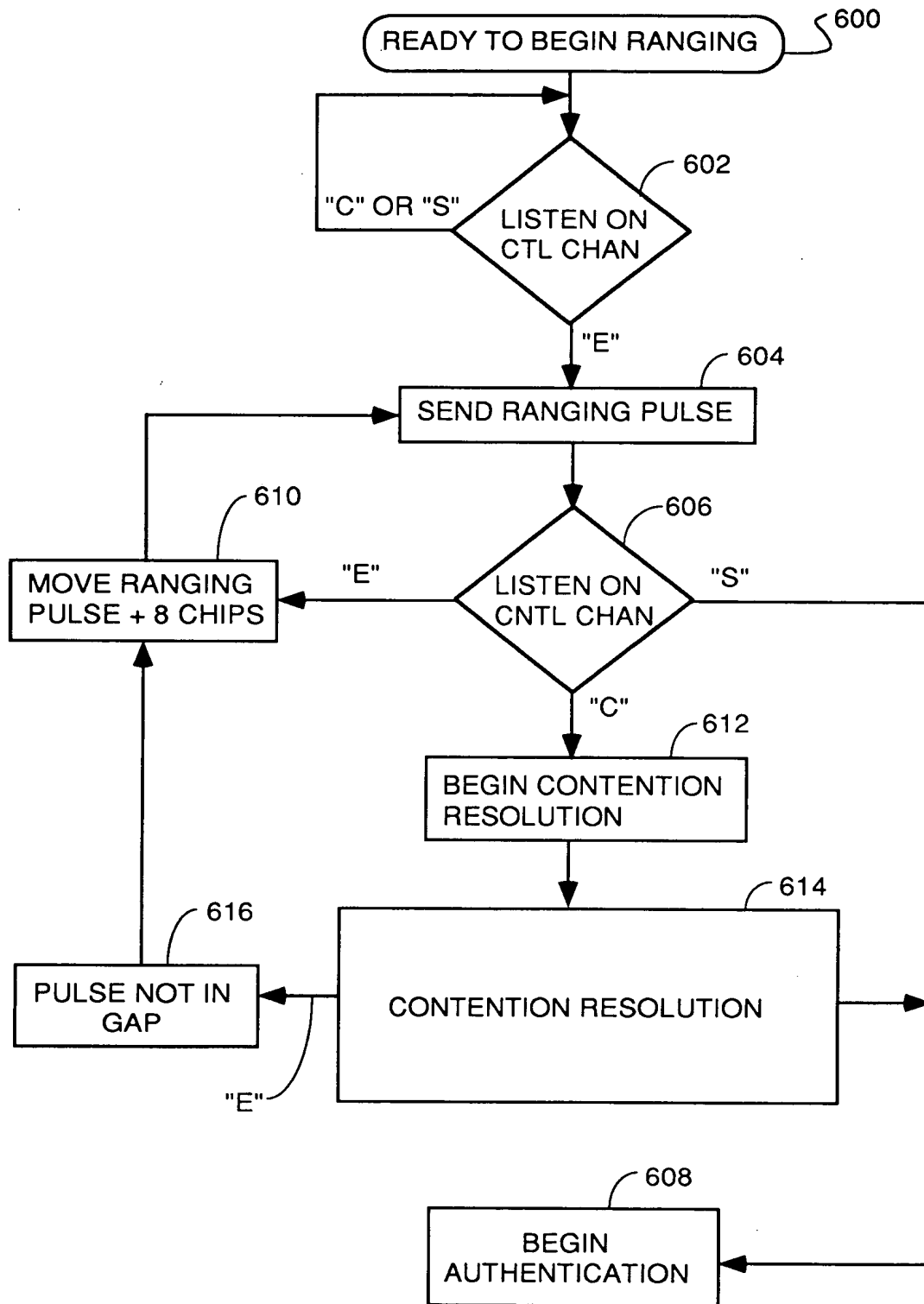


FIG. 44



RU RANGING
FIG. 45

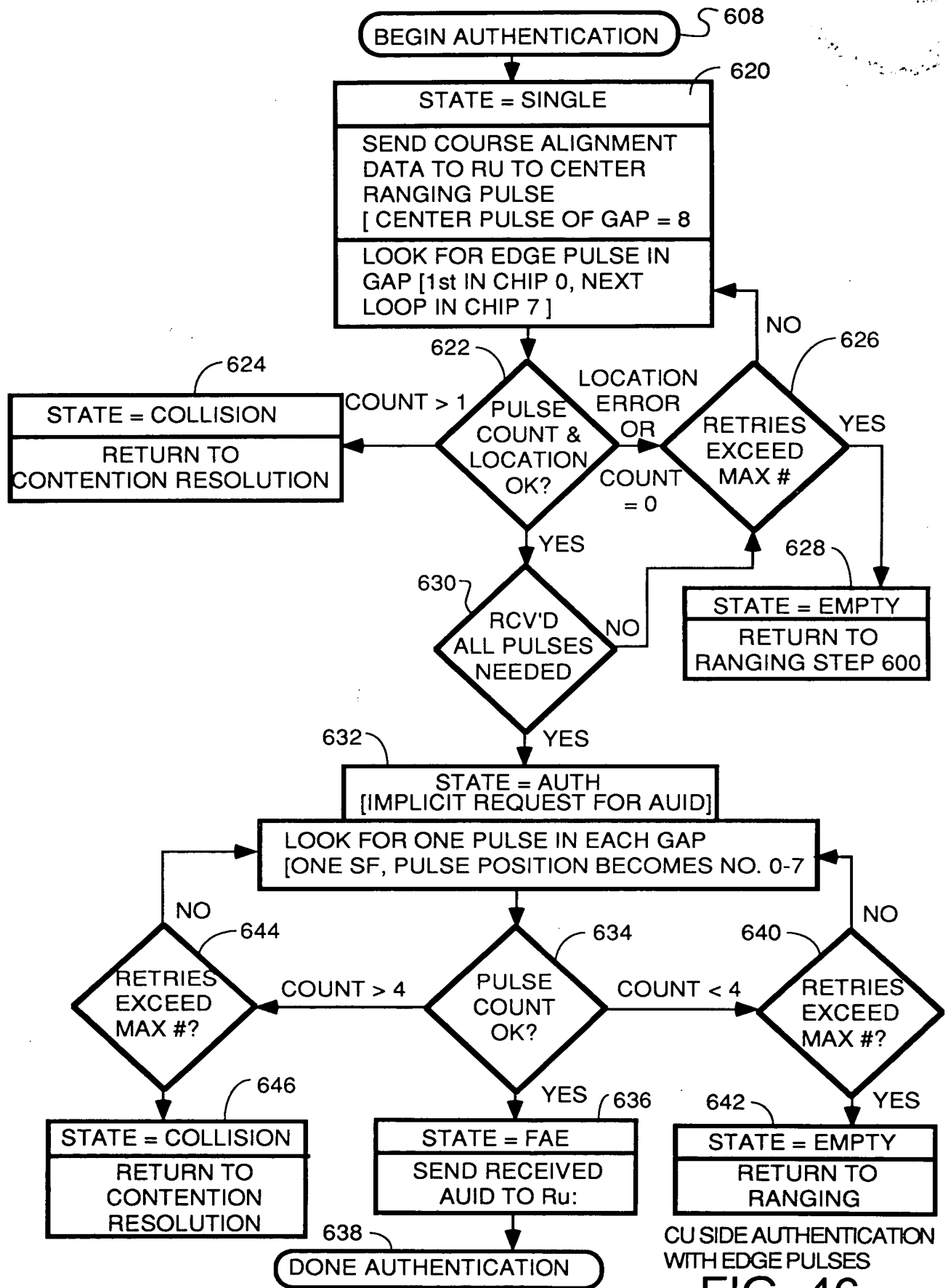
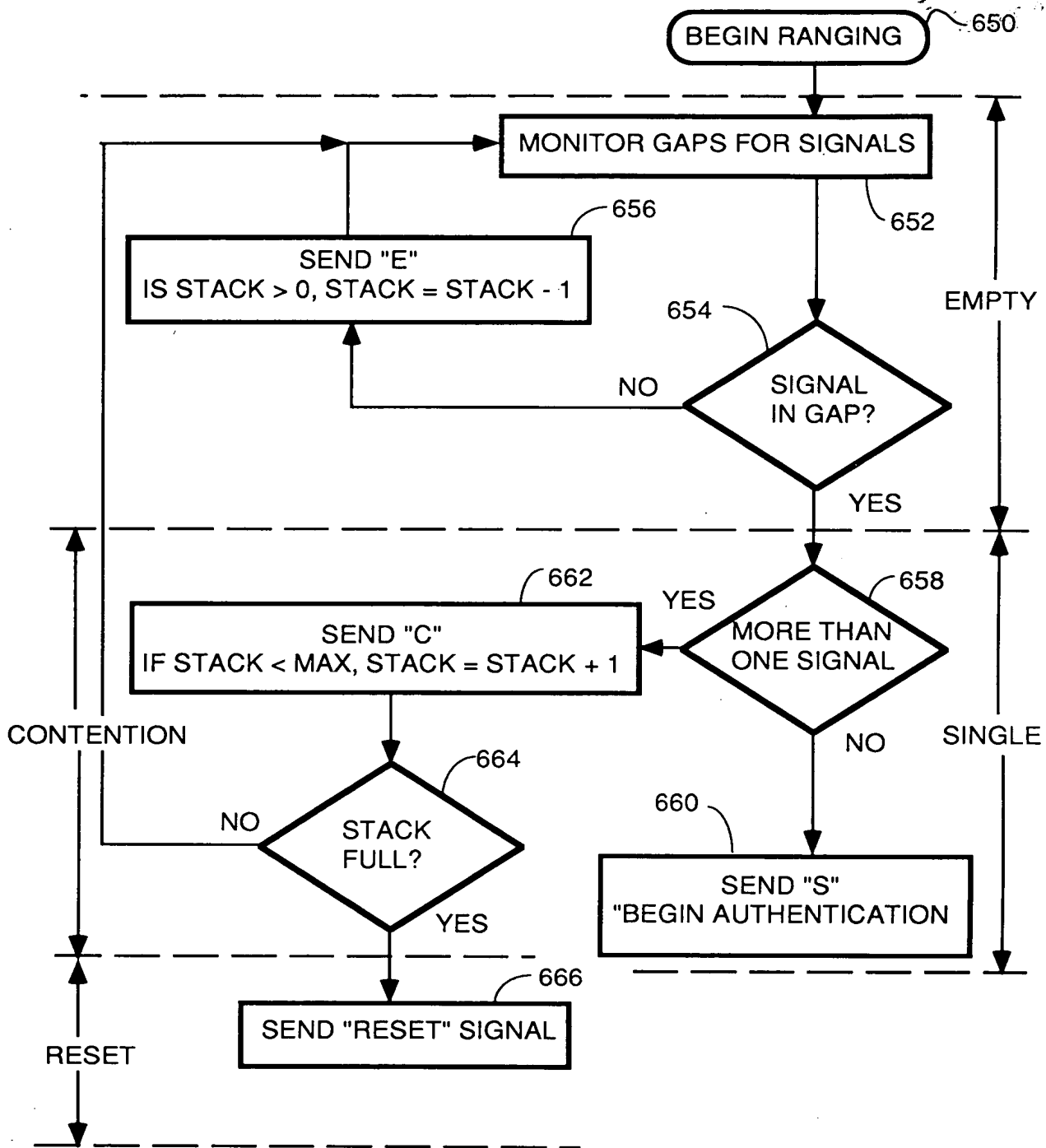
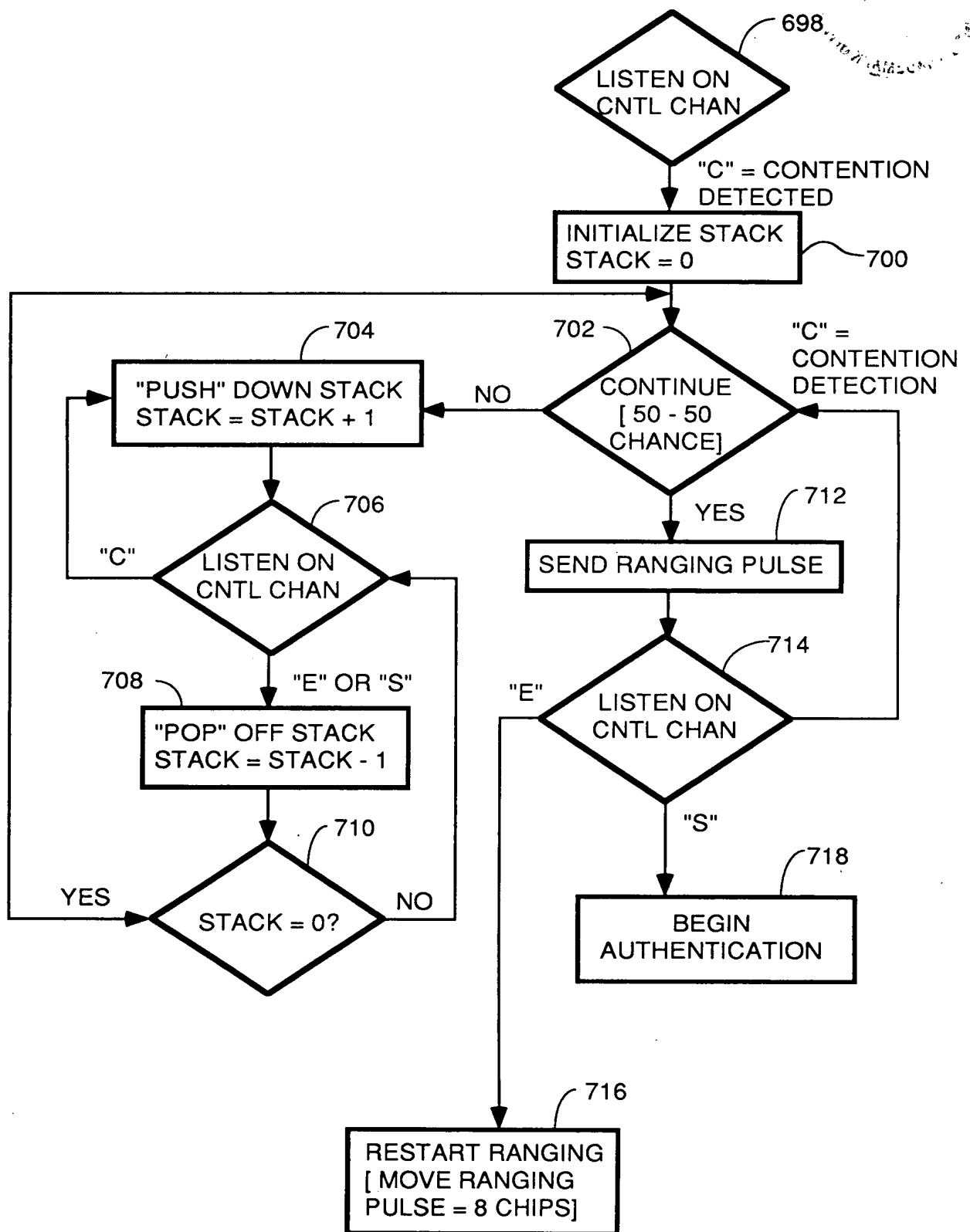


FIG. 46



CU RANGING AND CONTENTION RESOLUTION

FIG. 47



CONTENTION RESOLUTION - RU
USING BINARY STACK

FIG. 48

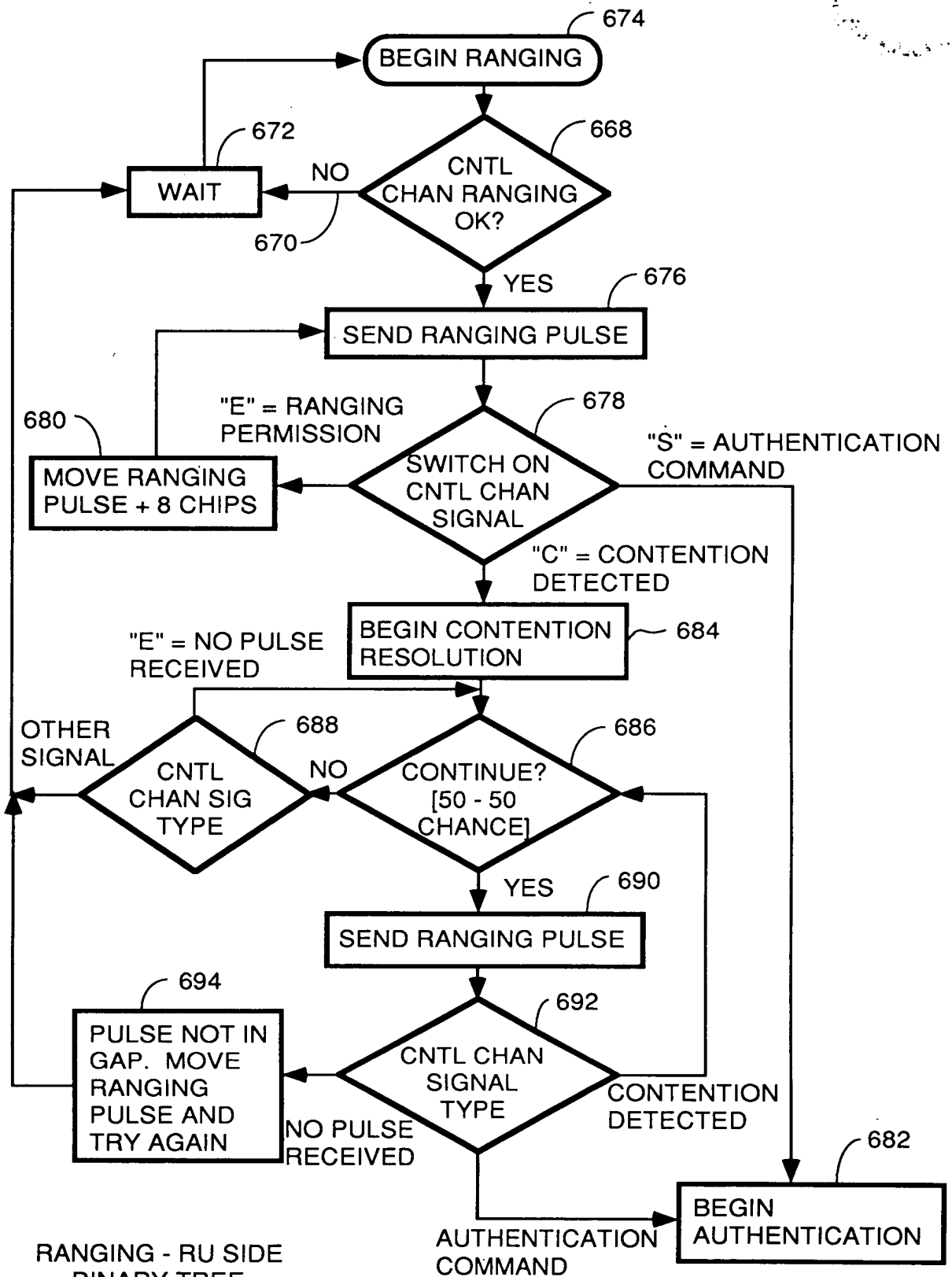


FIG. 49

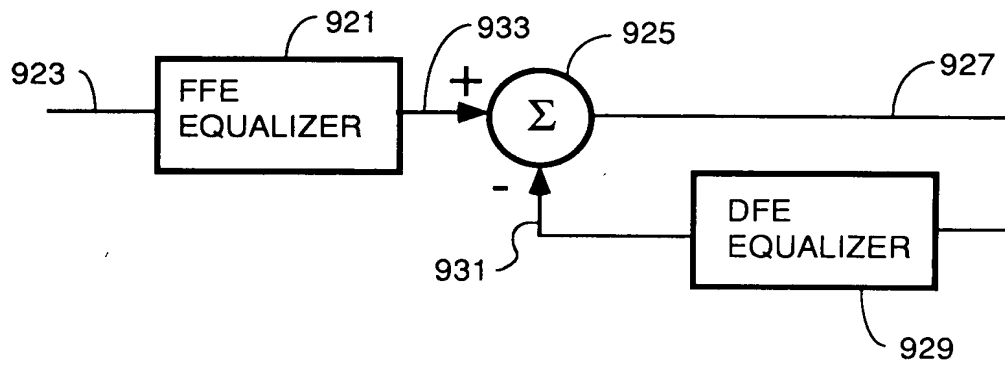


FIG. 50

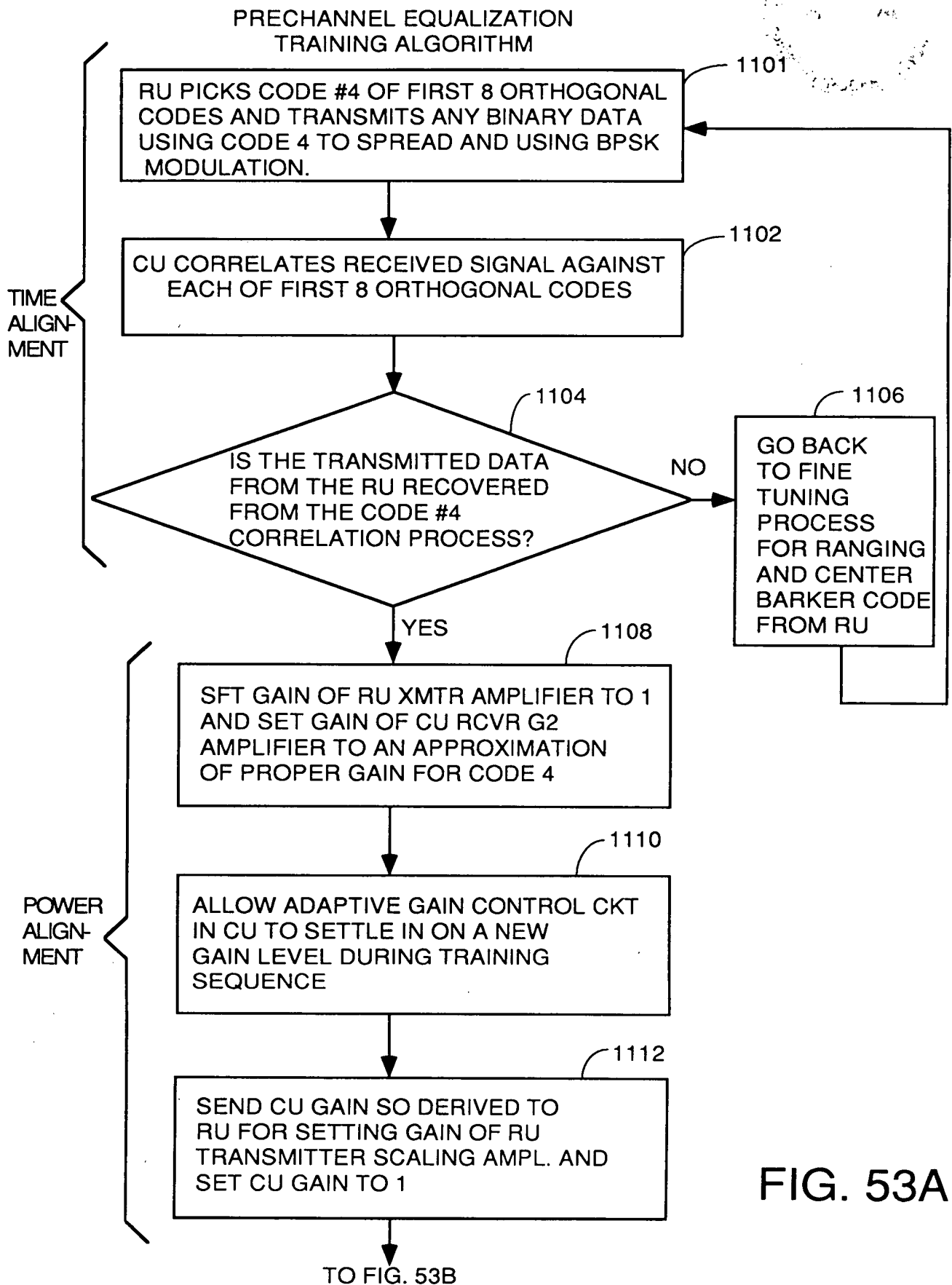


FIG. 53A

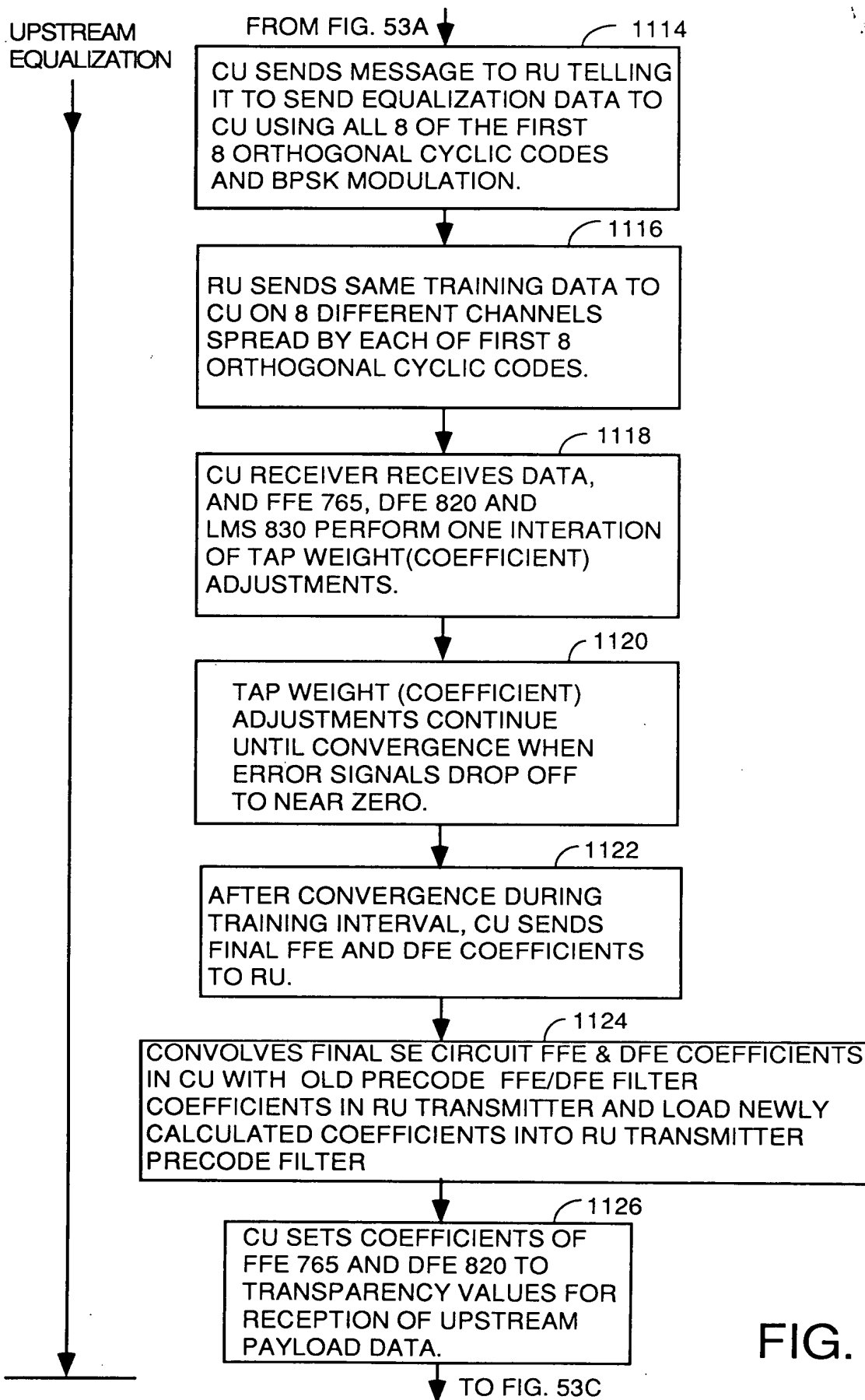


FIG. 53B

Patented
Mar 10 1999
U.S. Pat. No. 5,811,149

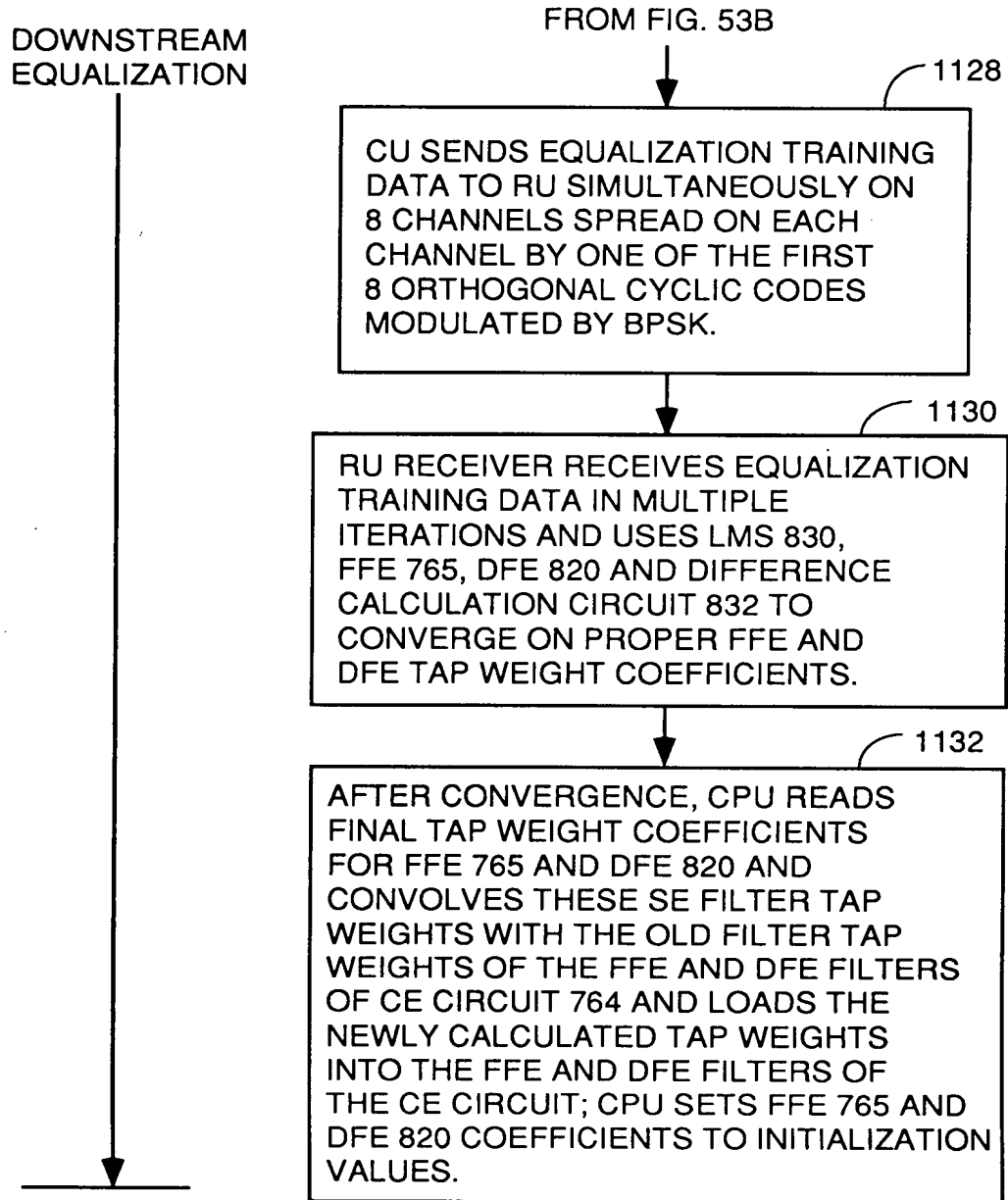


FIG. 53C

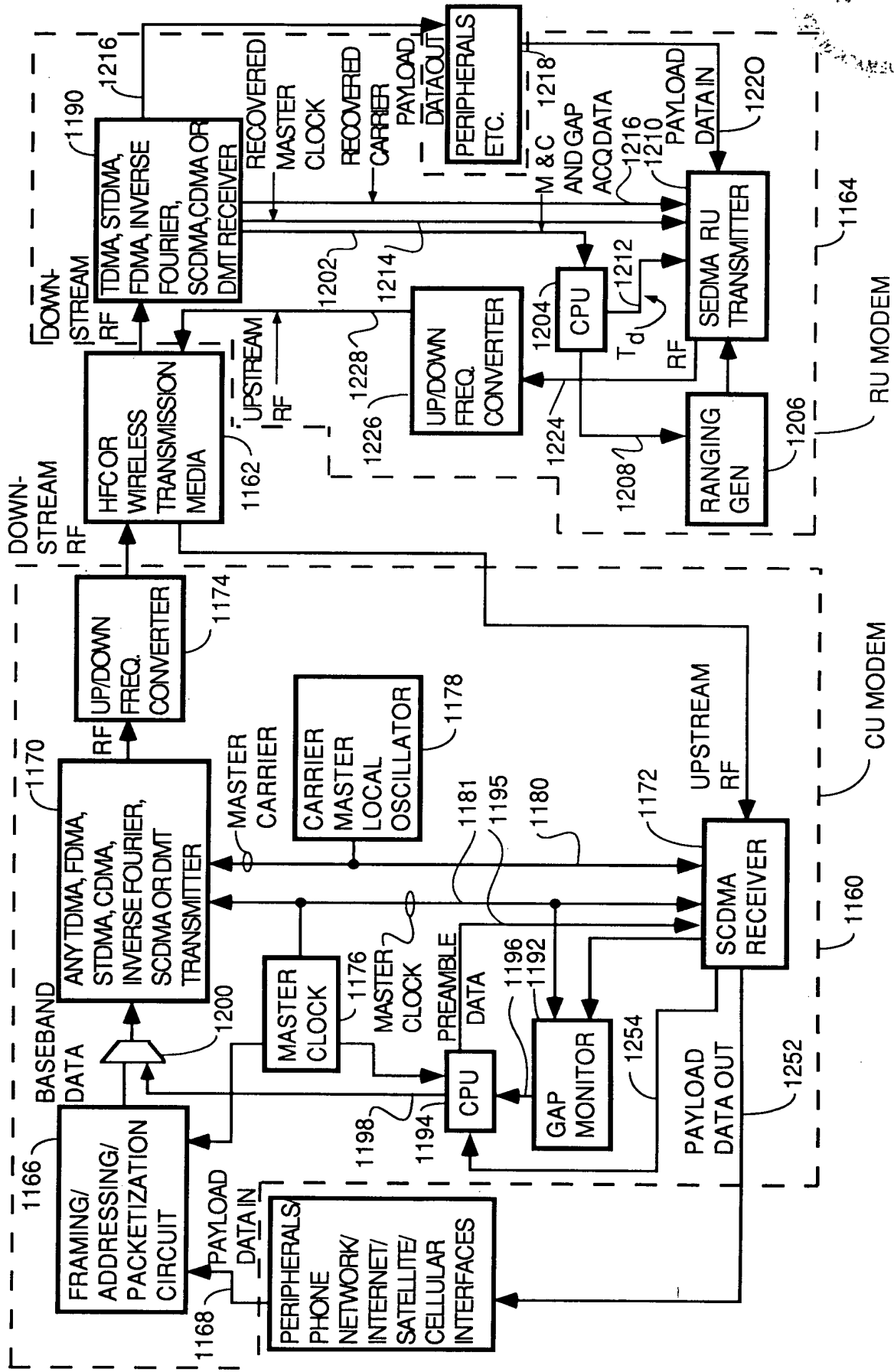
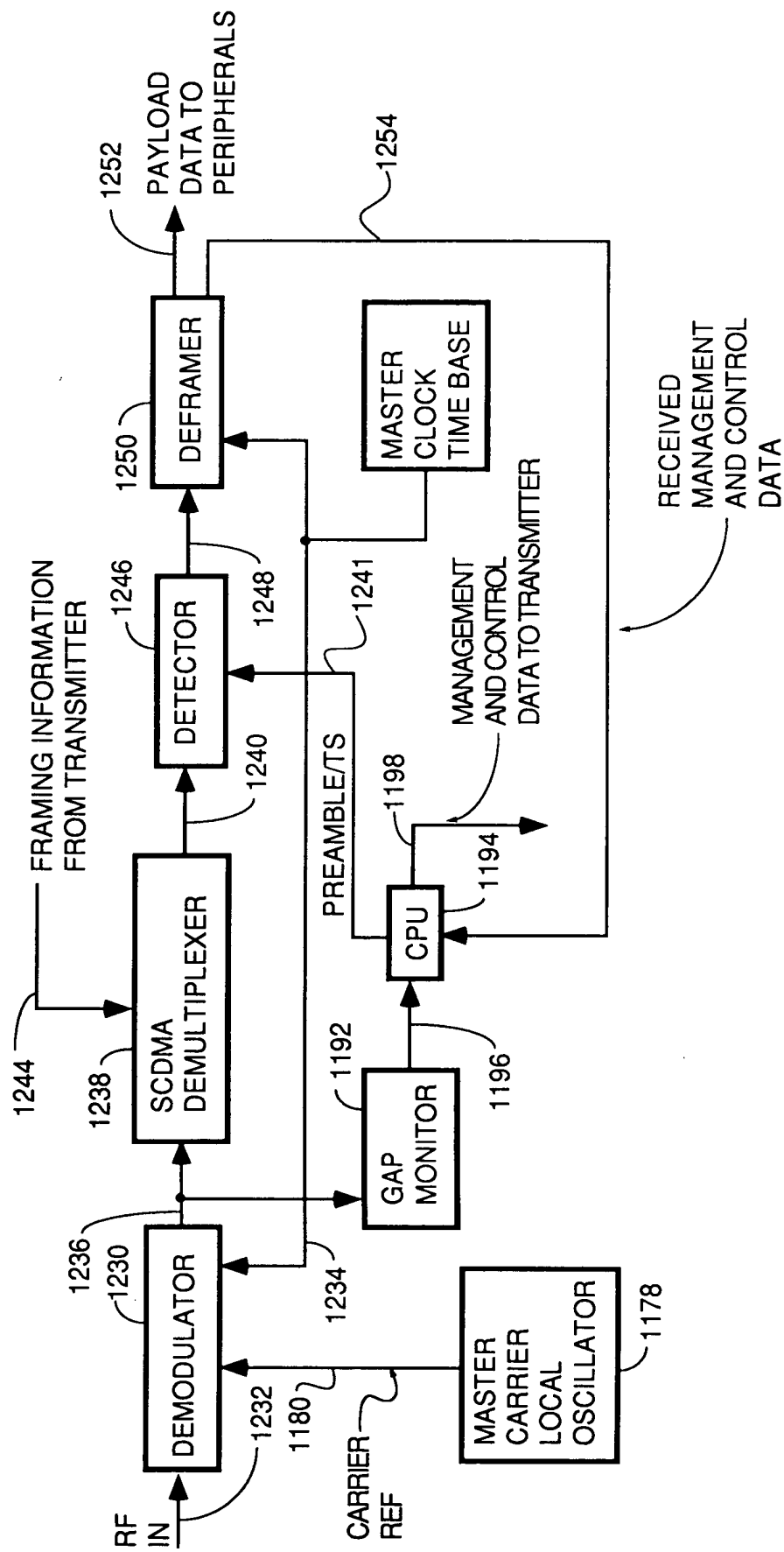


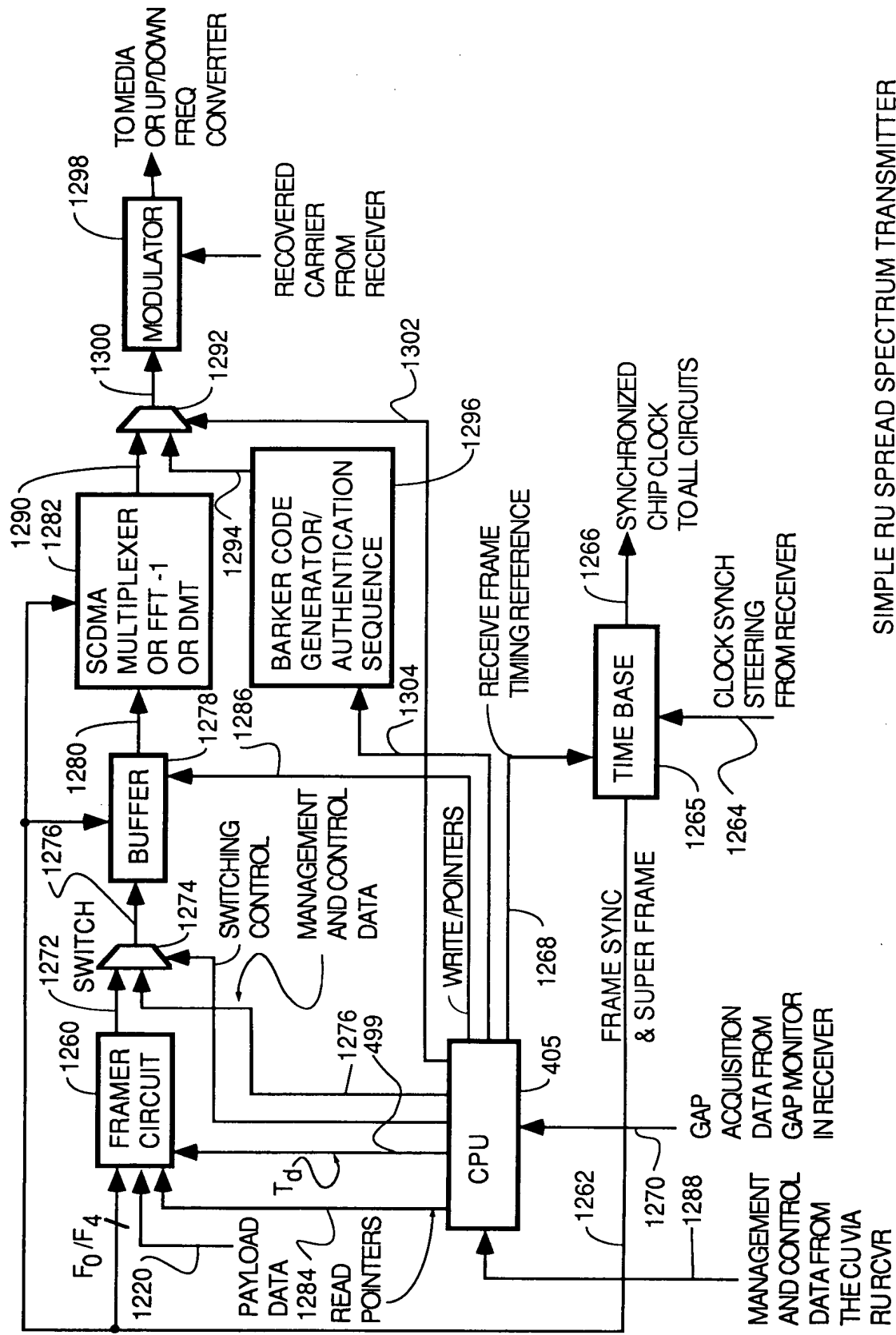
FIG. 54



SIMPLE CU SPREAD SPECTRUM RECEIVER

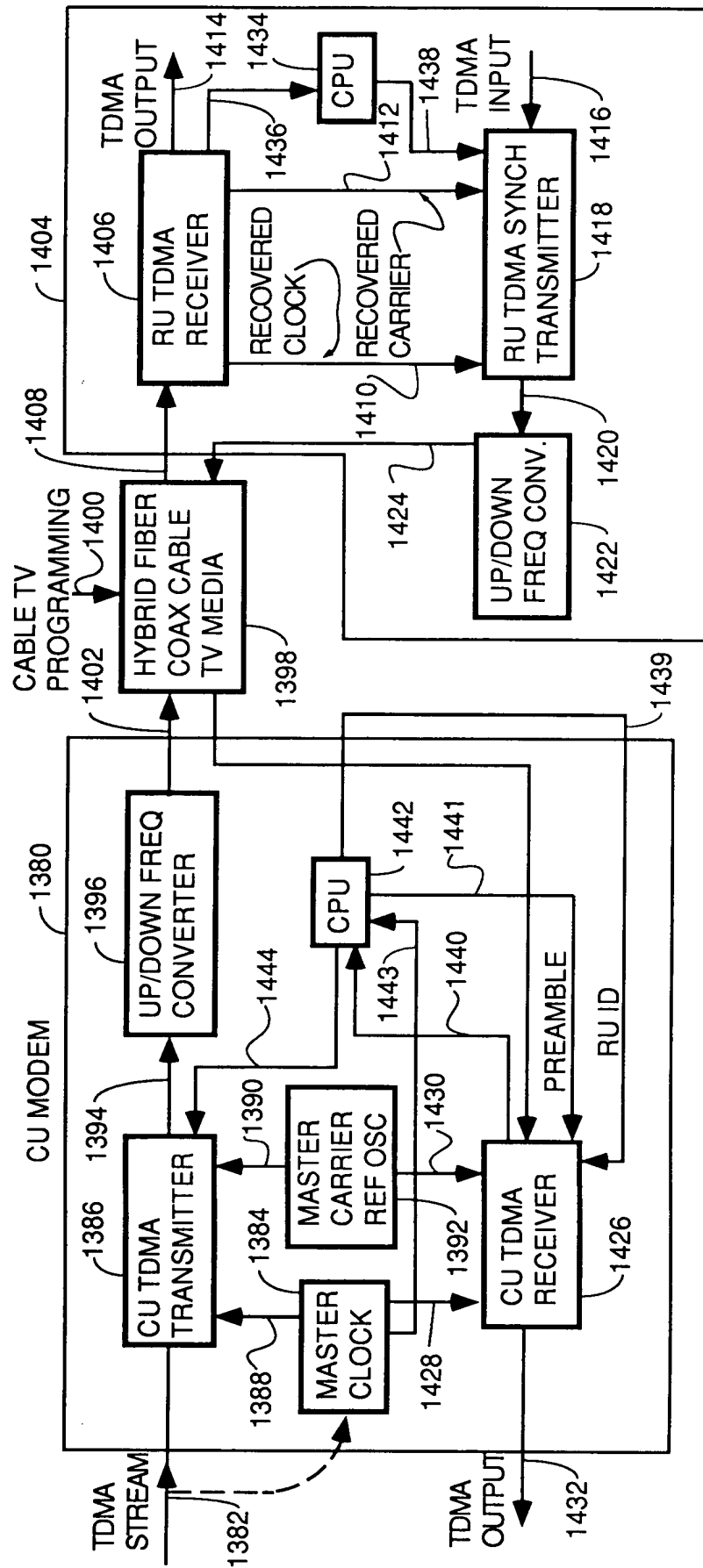
FIG. 55





SIMPLE RU SPREAD SPECTRUM TRANSMITTER

FIG. 56



SYNCHRONOUS TDMA SYSTEM

FIG. 57

OFFSET (CHIPS)	1B ASIC		2A ASIC	
	RGSRH	RGSRL	RGSRH	RGSRL
0	0x0000	0x8000	0x0001	0x0000
1/2	0x0000	0xC000	0x0001	0x8000
1	0x0000	0x4000	0x0000	0x8000
-1	0x0001	0x0000	0x0002	0x0000

FIG. 58

TRAINING ALGORITHM

SE FUNCTION

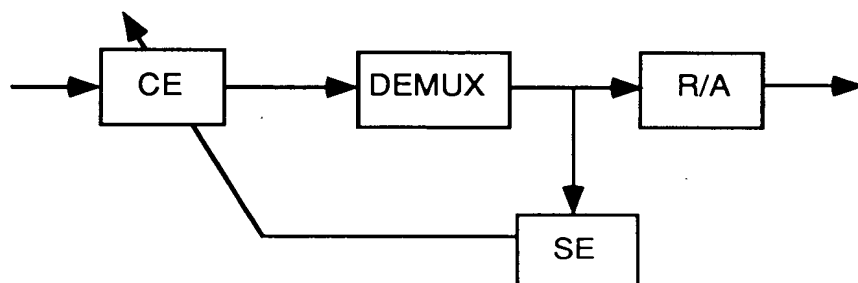


FIG. 59

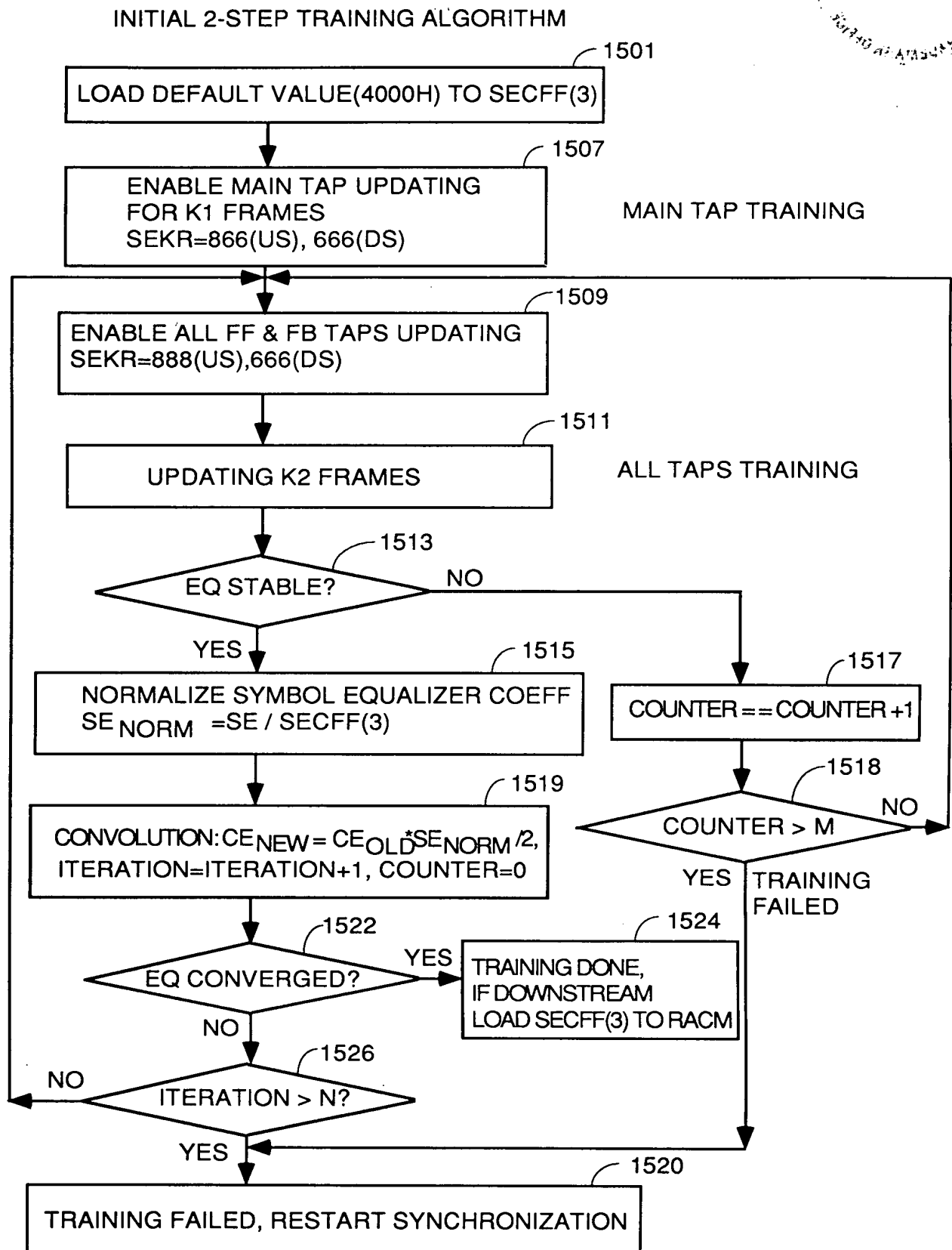


FIG. 60



EQ STABILITY CHECK

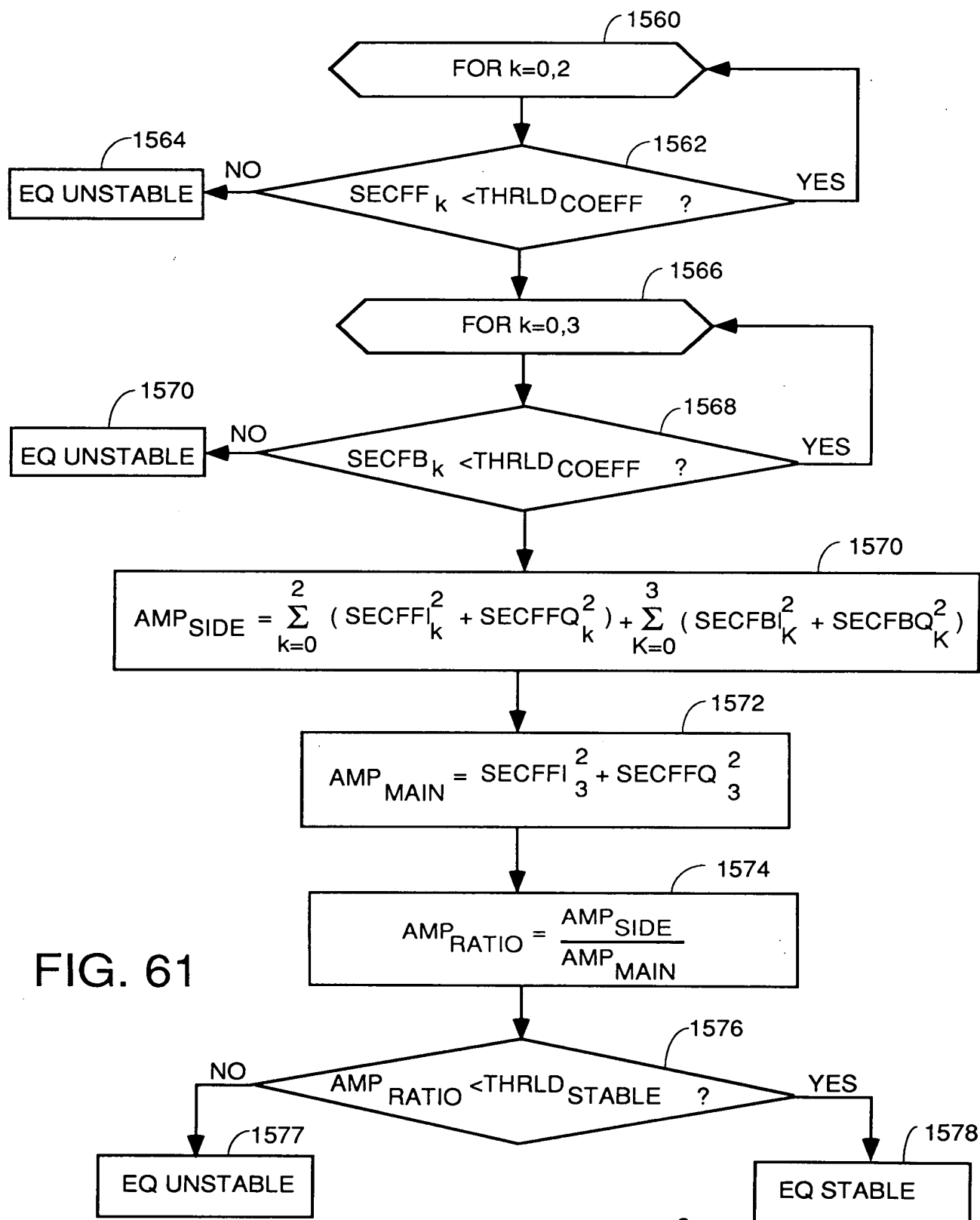
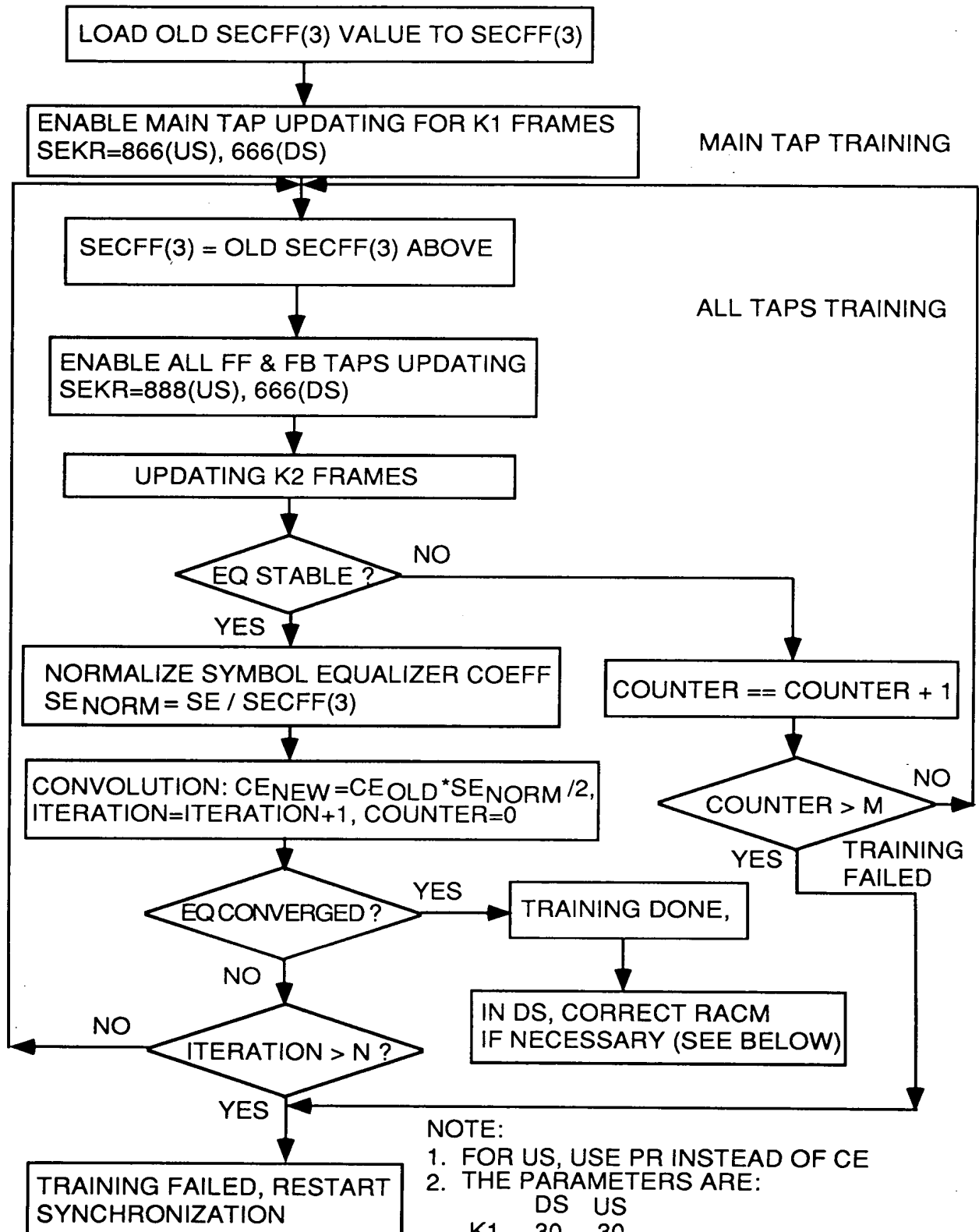


FIG. 61

NOTE: THRLD_COEFF = 7F00H

THRLD_STABLE = 10⁻³

PERIODIC 2-STEP TRAINING ALGORITHM



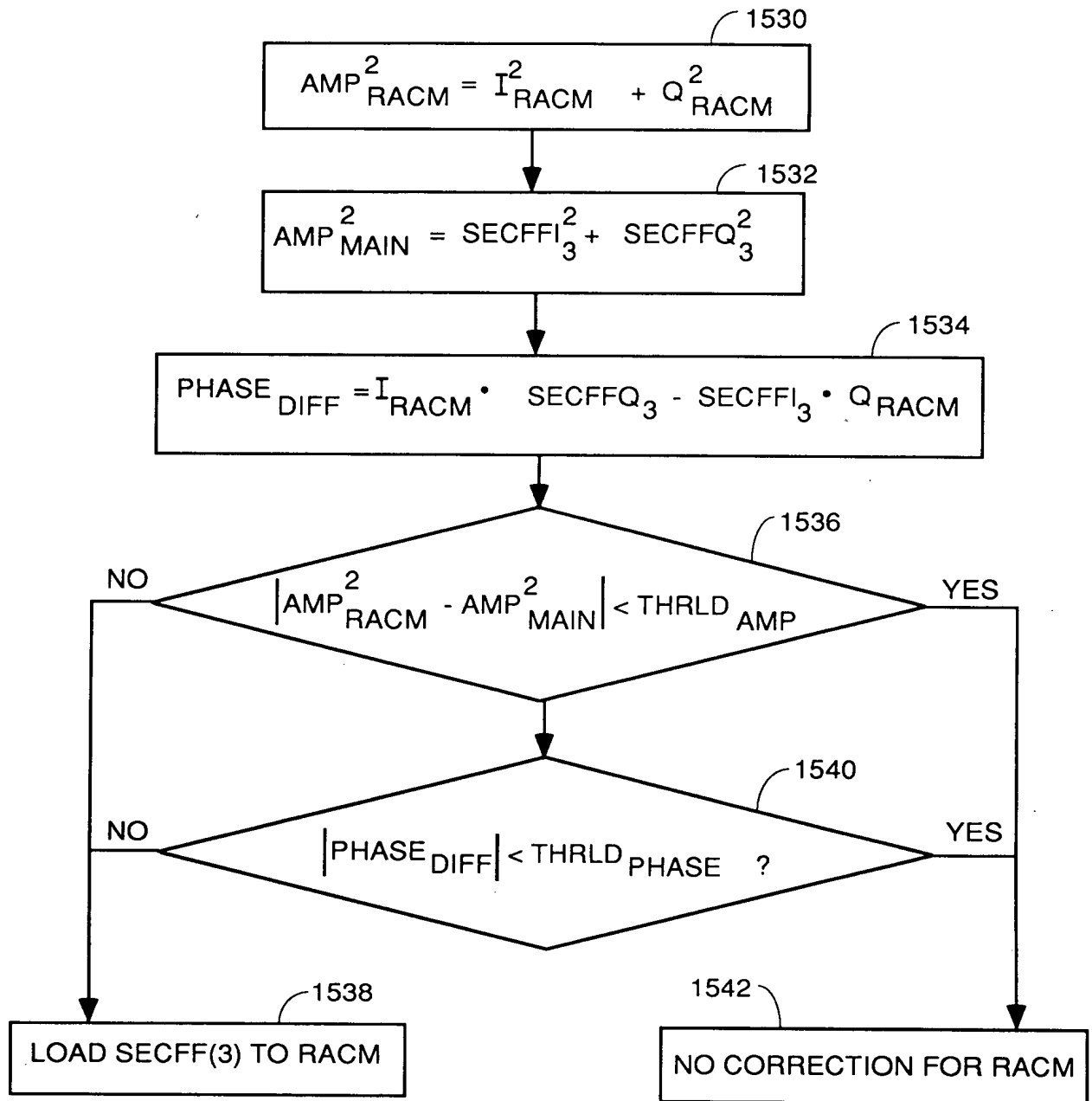
NOTE:

1. FOR US, USE PR INSTEAD OF CE
2. THE PARAMETERS ARE:

	DS	US
K1	30	30
K2	20	30
N	5	3
M	3	3

FIG. 62

RACM CORRECTION

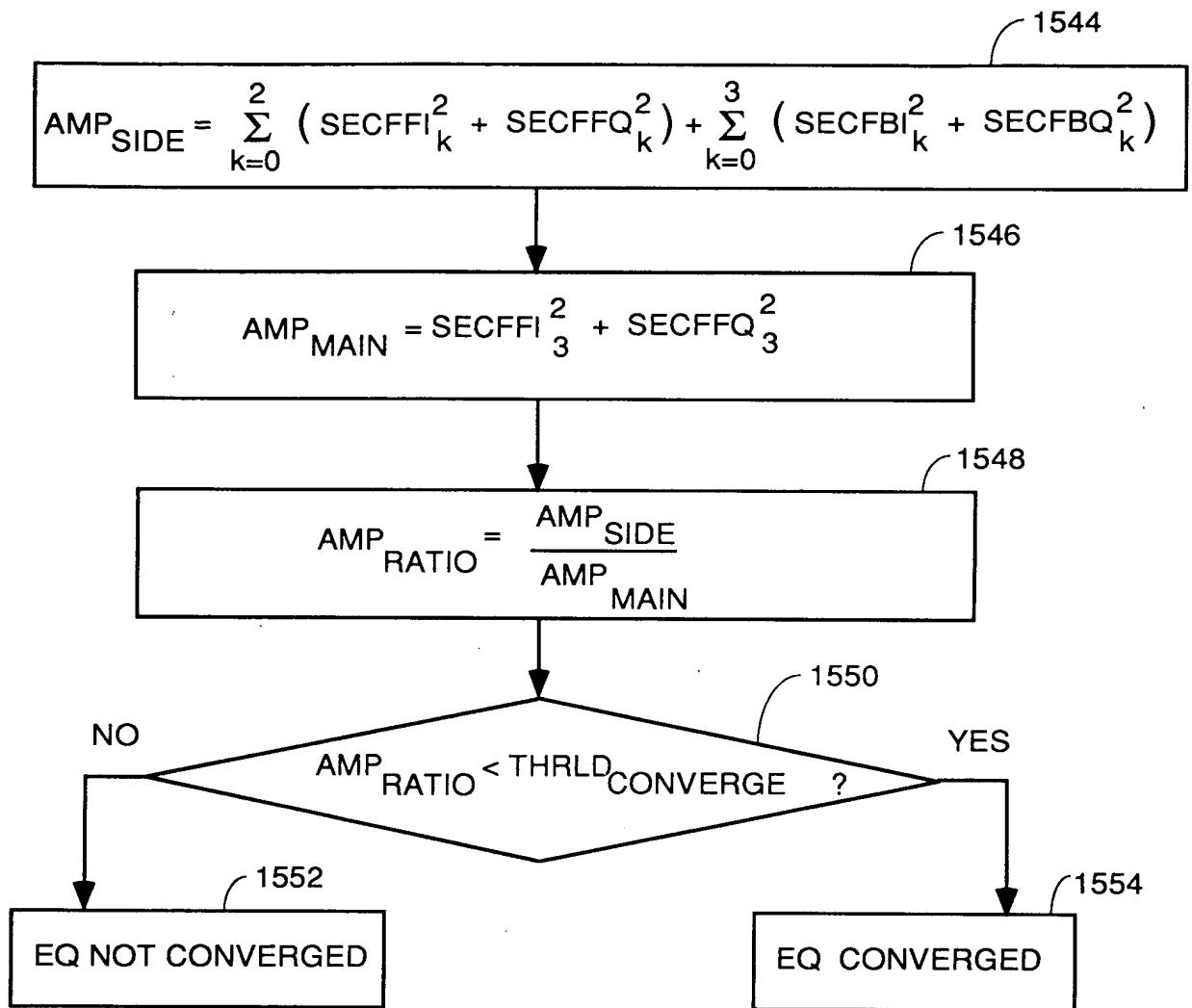


NOTE: $THRLD_{AMP} = TBD$
 $THRLD_{PHASE} = TBD$

ROTATIONAL AMPLIFIER CORRECTION

FIG. 63

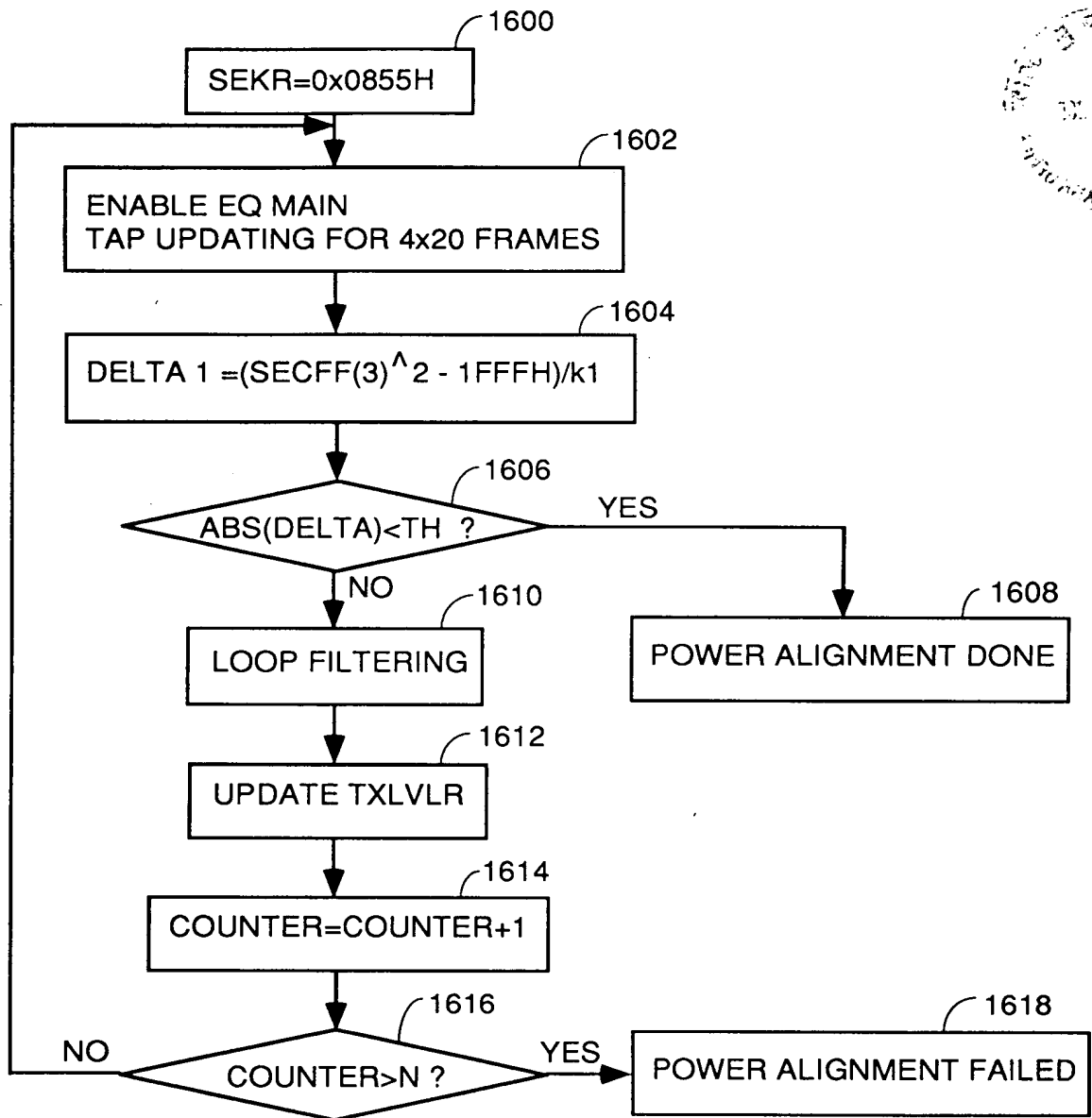
EQ CONVERGENCE CHECK



NOTE: THRLD_CONVERGE = 10^{-5}

FIG. 64

POWER ALIGNMENT FLOW CHART



NOTE: TH = 600H

N = 12

FIG. 65

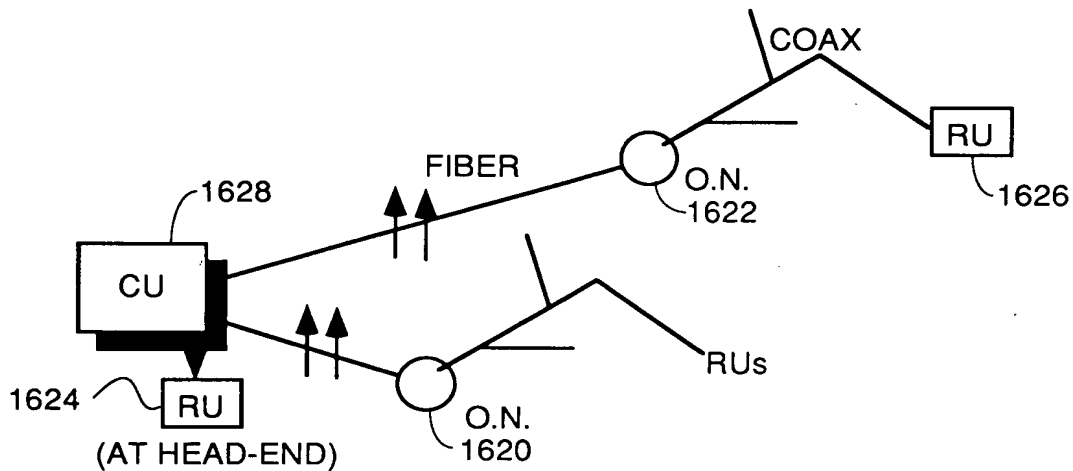
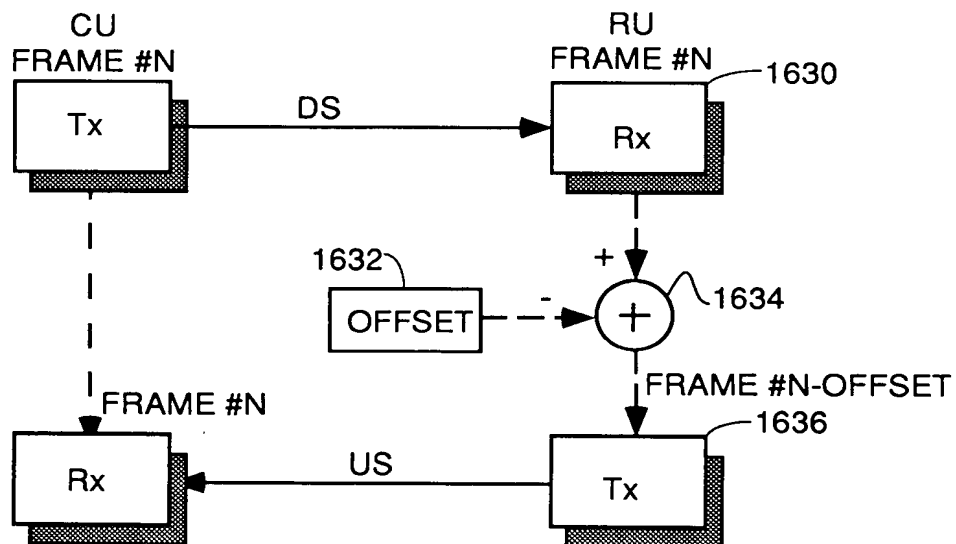


FIG. 66



TOTAL TURN AROUND (TTA) IN FRAMES = OFFSET

FIG. 67

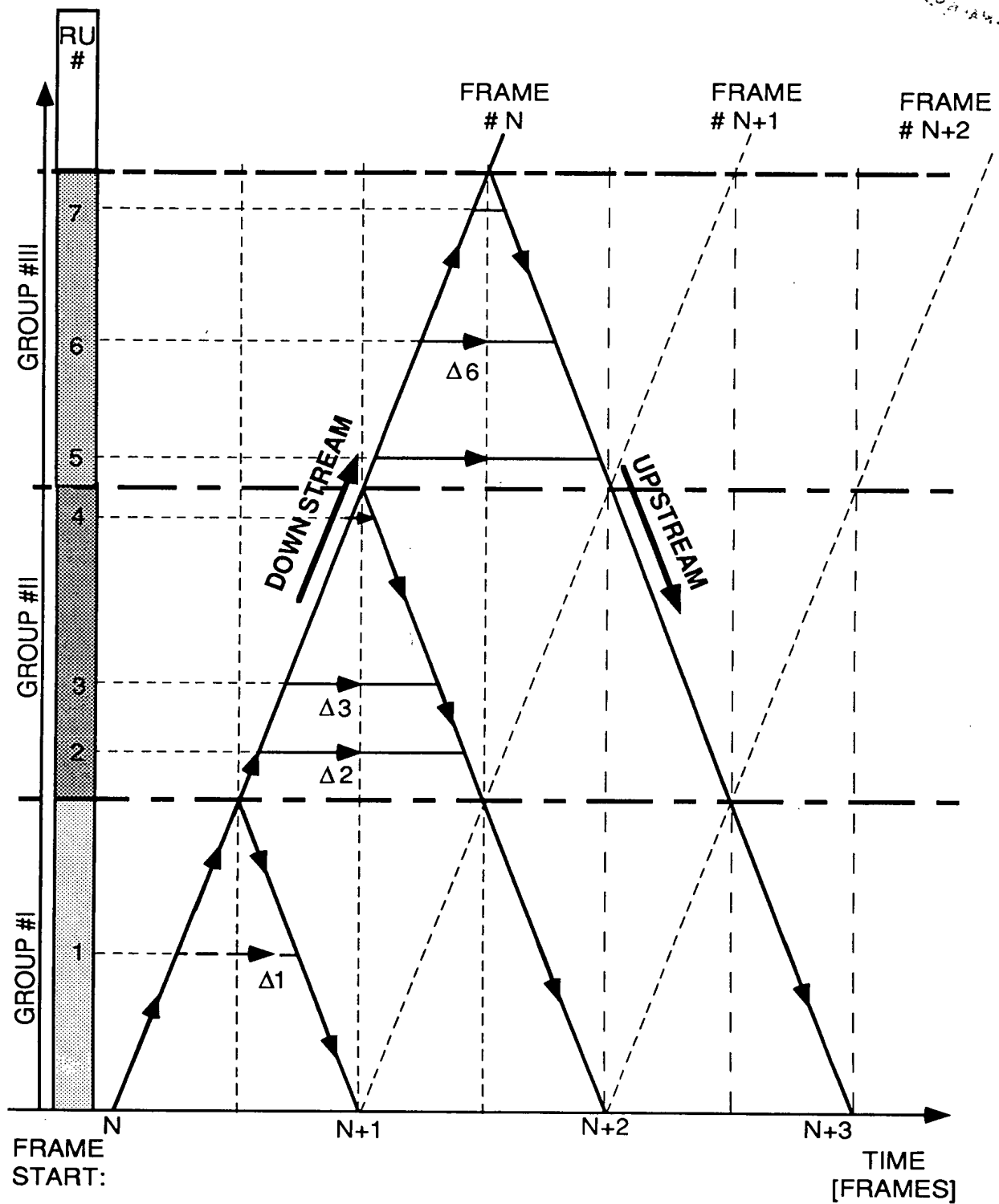
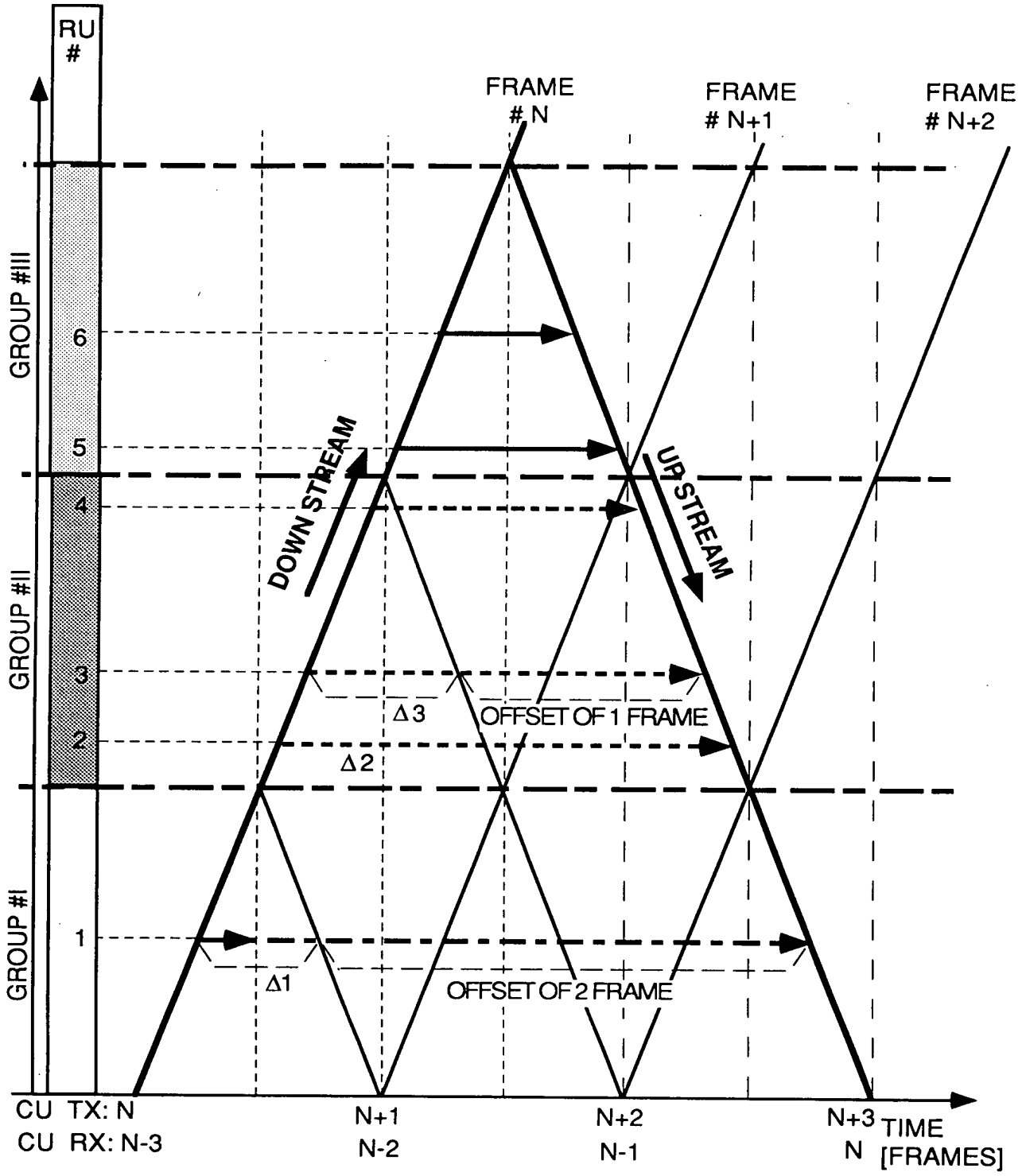


FIG. 68



CONTROL MESSAGE (DOWNSTREAM) AND FUNCTION (UPSTREAM)
PROPAGATION IN A 3 FRAMES TTA CHANNEL

FIG. 69

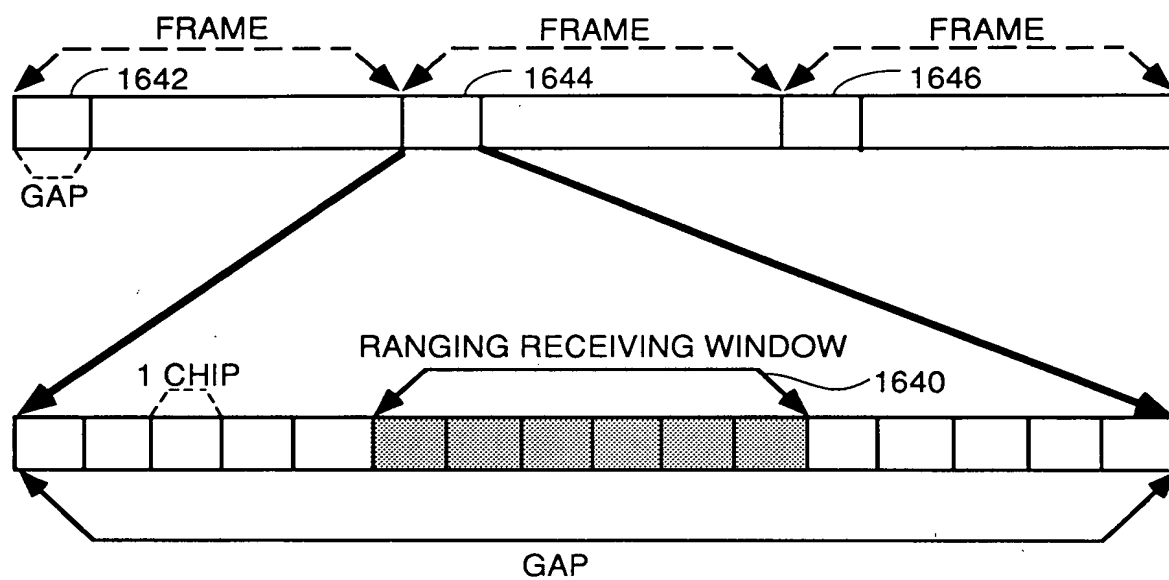
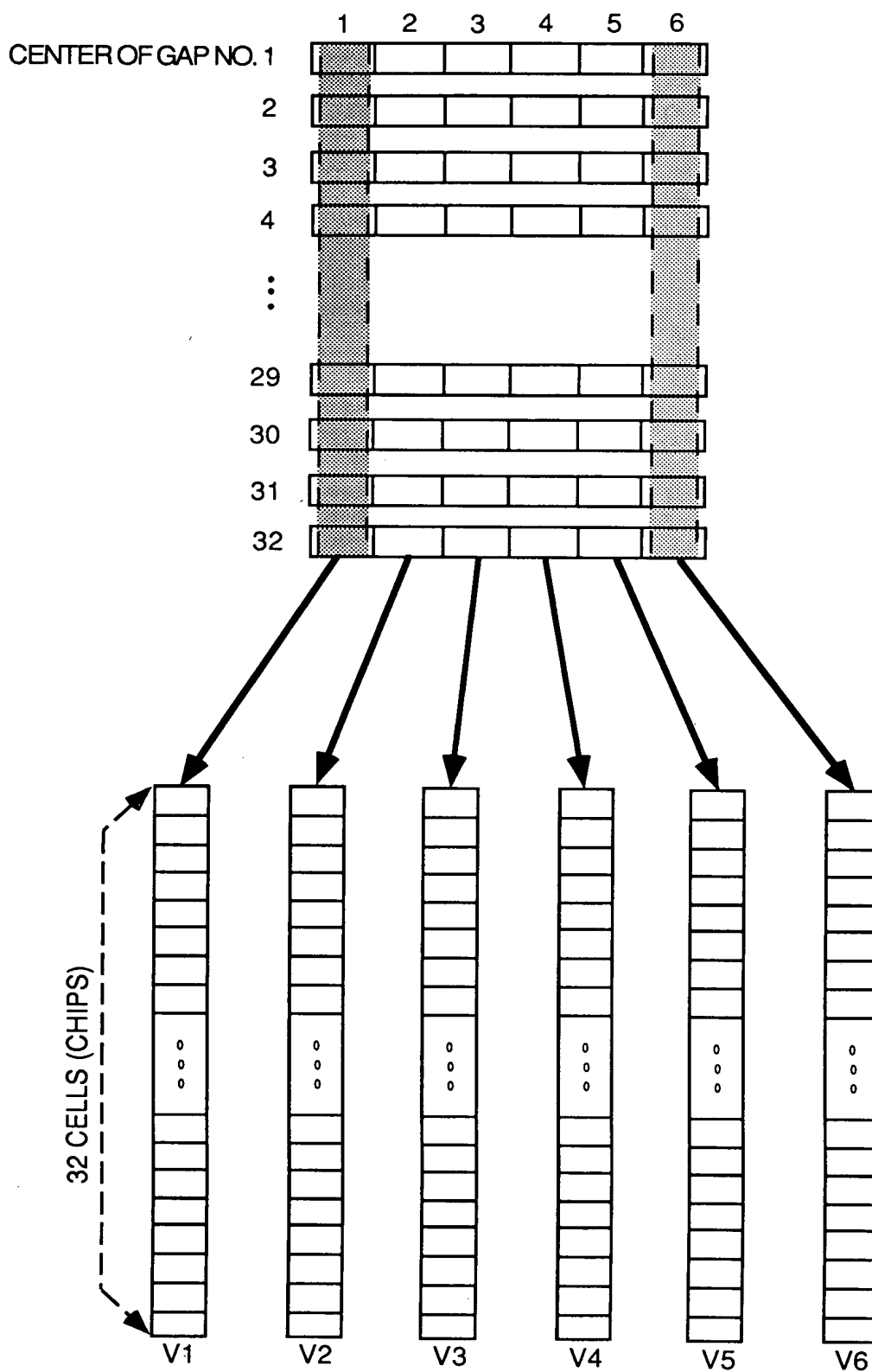


FIG. 70

OFFICE
OF THE
ATTORNEY GENERAL
STATE OF CALIFORNIA



OVERALL VIEW OF THE CU SENSING WINDOWS
IN A "BOUNDLESS RANGING" ALGORITHM

FIG. 71

CHIP\FR	1	2	3	4	5	6	7		33
1	0	0	1	0	0	1	1	...	0
2	1	0	0	1	1	1	1	...	
3	0	0	0	1	1	1			
4	0	0	0	1	0	0	0	...	0
5	0	1	0	0	1				
6	0	0	1	1	1				
7	0	0	0	1	1				
8	0	0	0	0	1	0	0	...	

FIG. 72